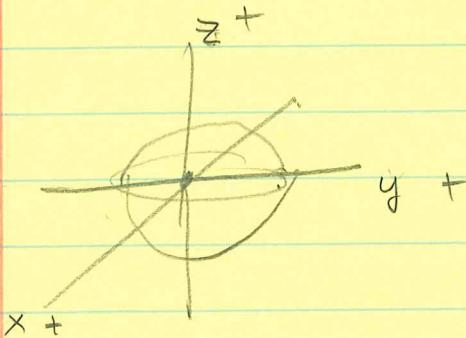


## SECTIONS 12.1 - 12.4.

## § 12.1 • Vectors + coord systems



- Right hand rule

- Drawing / Visualizing

$$\text{e.g. } x^2 + y^2 + z^2 = 1$$

spn, radius  $\neq$

center at  $(0,0,0)$

$$\star ((\text{sphere} = (x-a)^2 + (y-b)^2 + (z-c)^2 = r^2))$$

- Distance between 2 pts  $(x_1, \dots, x_n) = \sqrt{x}$

$$(y_1 - \dots - y_n) = \sqrt{y}$$

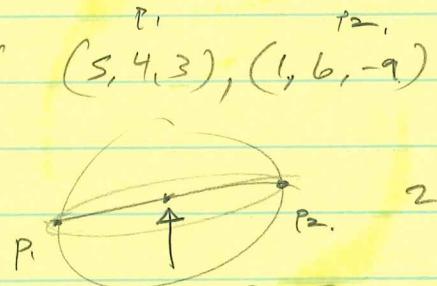
is  $\sqrt{\sum_i (x_i - y_i)^2}$  (pythagorean theorem).

• class : Distance from  $(1, 2, 3)$  to  $(5, 6, 7)$   
 $= \sqrt{4^2 + 4^2 + 4^2} = 4\sqrt{3} \approx 11$

• class (22)

Find eqn of sphere if  $(3, 4, 3), (1, 6, -9)$  is a line of diameter.

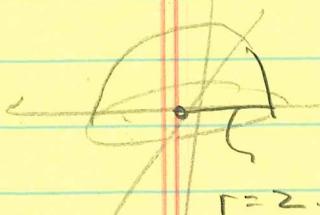
(1) Picture



$$M = \frac{P_1 + P_2}{2} = (3, 5, -3)$$

$$\begin{aligned} r &= |P_2 - M| = \sqrt{(-2)^2 + 1^2 + (-9-3)^2} = \sqrt{4+1+36} = \sqrt{41} \\ &\Rightarrow (x-3)^2 + (y-5)^2 + (z+3)^2 = 41 \end{aligned}$$

• class 40 • find equations defining solid upper hemisphere,  $r=2$ , center at origin.

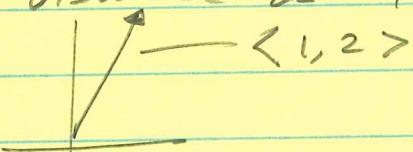


•  $x^2 + y^2 + z^2 \leq 4, z \geq 0$

(1)

§ 12.2 Vectors : a. directed quantity  
Speed is just a quantity, velocity is a vector.

Write a vector as  $\langle a, b \rangle$ , visualize as tail at  $(0,0)$ , head at  $(a,b)$ , e.g.

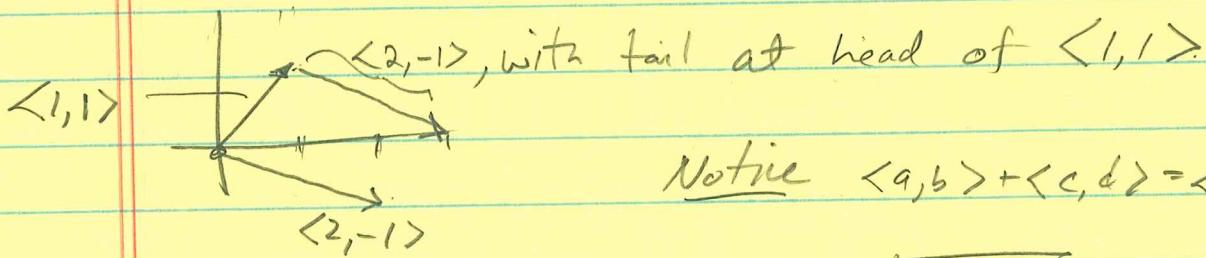


scale, add, subtract in obvious fashion:

$$\langle a, b \rangle + \langle c, d \rangle = \langle a+c, b+d \rangle, k\langle a, b \rangle = \langle ka, kb \rangle$$

Pictorially adding vectors = put tail of one at head of second.

$$\text{e.g. } \langle 1, 1 \rangle + \langle 2, -1 \rangle = \langle 3, 0 \rangle$$



$$\text{Notice } \langle a, b \rangle + \langle c, d \rangle = \langle c, d \rangle + \langle a, b \rangle.$$

Length of  $\vec{v} = \langle v_1, \dots, v_n \rangle = \sqrt{\sum v_i^2}$

↑  
entries are components

See P 802 for properties of vectors.

In  $\mathbb{R}^3$ ,  $\vec{i} = \langle 1, 0, 0 \rangle$ ,  $\vec{j} = \langle 0, 1, 0 \rangle$ ,  $\vec{k} = \langle 0, 0, 1 \rangle$

Vector is unit vector if  $|\vec{v}| = 1$

• Class

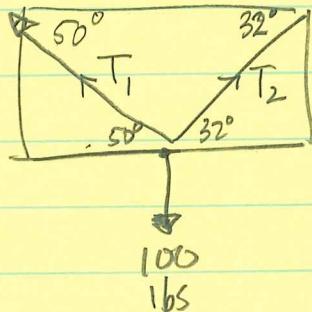
• Compute length of  $\vec{v} = \langle 1, 2, 3 \rangle$

• Find unit vector  $\vec{u}$  in same direction

SOLN  $|\vec{v}| = \sqrt{1^2 + 2^2 + 3^2} = \sqrt{14}$ ,  $\vec{u} = \vec{v}/|\vec{v}|$   $\square$

(2)

## Application (Example 7, p 804)



Find  $T_1, T_2$ .

Break into components:

$$T_1 = |T_1| \cos 50 \hat{i} + |T_1| \sin 50 \hat{j}$$

$$T_2 = |T_2| \cos 32 \hat{i} + |T_2| \sin 32 \hat{j}$$

Ask class What info is not used?

Answer: Force  $\uparrow = 100 \text{ lbs}$ ,

Force  $\rightarrow = 0$

so:  $|T_1| \cos 50 = |T_2| \cos 32 \Rightarrow |T_1| = \frac{\cos 32}{\cos 50} |T_2|$

$|T_1| \sin 50 + |T_2| \sin 32 = 100$

$$\frac{\cos 32}{\cos 50} |T_2| \sin 50 + |T_2| \sin 32 = 100$$

$$|T_2| \approx 65 \Rightarrow |T_1| \approx 85.$$

Class: Find unit vector  $\parallel$  to tangent line to  $y = x^2$  at  $(2, 4)$ .

Solu: tan line has slope  $y' = 2x$  (at  $(2, 4)$ ) = 4.

so vector is  $\langle 1, 4 \rangle$  (1 over, 4 up)

unit = divide by  $\sqrt{1^2 + 4^2} = \sqrt{17} \Rightarrow \frac{\langle 1, 4 \rangle}{\sqrt{17}}$

(3)

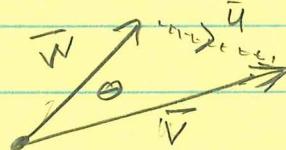
## § 1.3. (First actual new tool) Dot product.

DEF  $\vec{v} = \langle v_1, \dots, v_n \rangle$ ,  $\vec{w} = \langle w_1, \dots, w_n \rangle$ ,  $\vec{v} \cdot \vec{w} = \sum_i v_i w_i$

Facts (1)  $|v| = \sqrt{v \cdot v}$  or  $\vec{v} \cdot \vec{v} = |v|^2$ .

(2)  $\vec{v} \cdot \vec{w} = |v||w|\cos\theta$ , where

**SUPER USEFUL**



Proof  $\vec{v} + \vec{w} = \vec{u}$

Law of cosines  $|u|^2 = |v|^2 + |w|^2 - 2|v||w|\cos\theta$

$$(v+w)(v-w) = v \cdot v - w \cdot w$$

$$v \cdot v - 2v \cdot w + w \cdot w = v \cdot v + w \cdot w - 2|v||w|\cos\theta$$

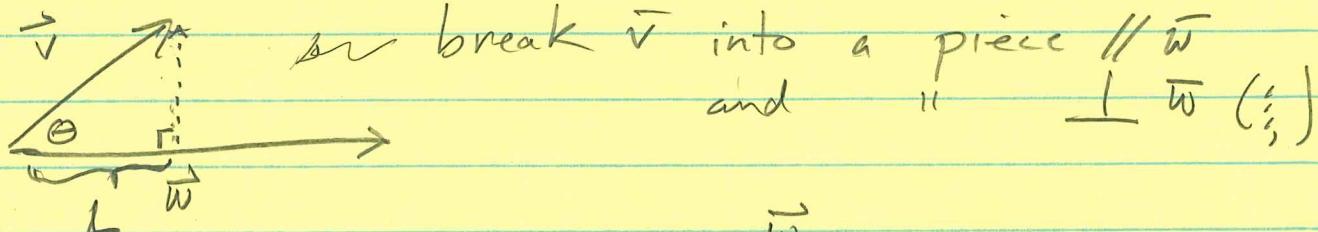
$$v \cdot w = |v||w|\cos\theta. \quad \blacksquare$$

Class find  $\angle$  between  $\langle 1, 1, 1, 1 \rangle$  and  $\langle 1, 2, 3, 4 \rangle$

$$\text{soln } v \cdot w = 10, |v| = 2, |w| = \sqrt{30}$$

$$10 = 2\sqrt{30} \cos\theta \Rightarrow \theta = \cos^{-1}\left(\frac{10}{2\sqrt{30}}\right) \blacksquare$$

Hardest part of today | Projection formula



Piece  $\parallel$  to  $\vec{w}$  is just  $L \cdot \frac{\vec{w}}{|w|}$ , and  $L$  is just  $|v|\cos\theta$ . But  $|w||v|\cos\theta = \vec{w} \cdot \vec{v}$

$$\text{so } L = \frac{\vec{w} \cdot \vec{v}}{|w|}$$

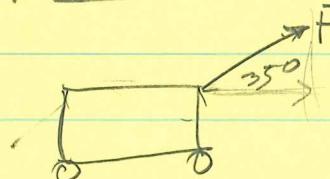
$\Rightarrow$  Piece  $\parallel$  is  $\frac{(\vec{w} \cdot \vec{v})}{|w|} \vec{w}$   $\blacksquare$

(4)

$$\underline{\text{Def}} \quad \text{Proj}_{\bar{w}} \bar{v} = \frac{\bar{v} \cdot \bar{w}}{\bar{w} \cdot \bar{w}} \bar{w}$$

Class Find  $\text{proj}_{\langle -2, 3, 1 \rangle} \langle 1, 1, 2 \rangle$  ( $= \frac{3}{14} \langle -2, 3, 1 \rangle$ )  
(Example 6)

Nice Application (Example 7) Work = force  $\times$  distance  
 $w = F \cdot D$



Wagon pulled 100 m along path using 70 N force.  
compute work

SOLN  $F = 70 \cos 35 i + 70 \sin 35 j$  Tales  
 $D = 100 i + 0 j$   
 $F \cdot D = 7000 \cos 35 = 5734 \text{ N/m}$  #

### § 12.4 Cross Product. (3D specific)

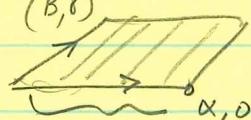
$$\bar{v}_1 = ai + bj + ck = \langle a, b, c \rangle$$

$$\bar{v}_2 = di + ej + fk = \langle d, e, f \rangle$$

Def  $\bar{v}_1 \times \bar{v}_2 = \det \begin{vmatrix} i & j & k \\ a & b & c \\ d & e & f \end{vmatrix} = i \begin{vmatrix} b & c \\ e & f \end{vmatrix} - j \begin{vmatrix} a & c \\ d & f \end{vmatrix} + k \begin{vmatrix} a & b \\ d & e \end{vmatrix}$

Recall  $\begin{vmatrix} x & y \\ z & w \end{vmatrix} = xw - yz \leftarrow \text{measures area}$

$\bar{v}_1 \times \bar{v}_2 \rightarrow$  twist so  $v_2 \approx \begin{pmatrix} \alpha \\ 0 \\ 0 \end{pmatrix}, v_1 = \begin{pmatrix} \beta \\ 0 \\ 0 \end{pmatrix}$



$$\begin{vmatrix} \alpha & \beta \\ 0 & 0 \end{vmatrix} = \alpha \beta = \text{base} \cdot \text{height} = \text{area}$$

Notice  $\bar{v} \cdot \bar{w} = \text{scalar}, \bar{v} \times \bar{w} = \text{vector}$

(5)

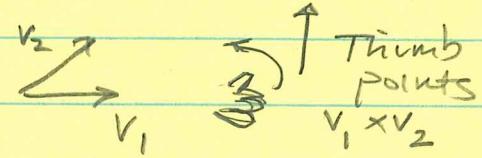
Theorem  $\mathbf{v}_1 \times \mathbf{v}_2 \perp \mathbf{v}_1, \mathbf{v}_2$

Proof: 
$$[i(bf-ce) - j(af-cd) + k(ae-bd)] \cdot [ai + bj + ck]$$

$$= \underbrace{a(bf-ce)}_{\cancel{a}} + \underbrace{b(af-cd)}_{\cancel{b}} + c(ae-bd) \quad \text{cancel.}$$

Facts  $\mathbf{v}_1 \times \mathbf{v}_2 = -\mathbf{v}_2 \times \mathbf{v}_1$

- Right hand rule  $\rightarrow$
- $|\mathbf{v}_1 \times \mathbf{v}_2| = |\mathbf{v}_1||\mathbf{v}_2| \sin \theta$

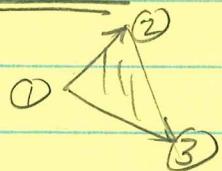


**Class** Find vector  $\perp$  to  $\langle 1, 1, 1 \rangle, \langle 1, 2, 3 \rangle$

Soln: 
$$\begin{vmatrix} i & j & k \\ 1 & 1 & 1 \\ 1 & 2 & 3 \end{vmatrix} = i - 2j + k. \quad \text{check } \langle 111 \rangle \cdot \langle 1, -2, 1 \rangle = 0$$

(1) (2) (3)

Application: Area of  $\triangle$  with vertices  $(1, -1, 1), (2, 0, 2), (2, 1, 4)$



$$\bar{v} = \vec{v_1} = \langle 1, 1, 1 \rangle$$

$$\bar{w} = \vec{v_2} = \langle 1, 2, 3 \rangle$$

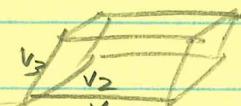
$$\text{Area} = \frac{1}{2} \parallel \text{gramm}$$

$$= \frac{1}{2} |\mathbf{v}_1||\mathbf{v}_2| \sin \theta = \frac{1}{2} |\langle 1, -2, 1 \rangle| = \frac{\sqrt{6}}{2}$$

Application

Volume of // piped

$$= \text{base} \cdot \text{height}$$



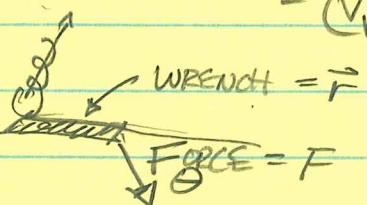
$$= |\mathbf{v}_1 \times \mathbf{v}_2| \cdot |\mathbf{v}_3| \cos \theta$$

$$= (\mathbf{v}_1 \times \mathbf{v}_2) \cdot \mathbf{v}_3 !$$

Example 6

Application

Torque



$$T = \vec{r} \times \vec{F}$$

$$|F = 40 \text{ N}, r = .25 \text{ m} \quad \theta = 75^\circ|$$

$$r = .25 \mathbf{j}, \quad F = 40 \cos 75 \mathbf{j} - 40 \sin 75 \mathbf{k}$$

Find T

Notice -  
Torque is  $\perp$  to  $r, F$  ✓

$$\begin{vmatrix} i & j & k \\ 0 & .25 & 0 \\ 0 & 0 & \cos \theta \end{vmatrix} = \frac{1}{4} \mathbf{p} \mathbf{l}$$