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To cite this article: Le Chen, Guannan Hu, Yaozhong Hu & Jingyu Huang (2016): Space-time fractional diffusions in Gaussian noisy environment, Stochastics

To link to this article: <http://dx.doi.org/10.1080/17442508.2016.1146282>



Published online: 18 Feb 2016.



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Space-time fractional diffusions in Gaussian noisy environment

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ABSTRACT

This paper studies the linear stochastic partial differential equation of fractional orders both in time and space variables $(\partial^\beta + \frac{\nu}{2}(-\Delta)^{\alpha/2})u(t, x) = \lambda u(t, x)\dot{W}(t, x)$, where \dot{W} is a general Gaussian noise and $\beta \in (1/2, 2)$, $\alpha \in (0, 2]$. The existence and uniqueness of the solution, the moment bounds of the solution are obtained by using the fundamental solutions of the corresponding deterministic counterpart represented by the Fox H-functions. Along the way, we obtain some new properties of the fundamental solutions.

ARTICLE HISTORY

Received 13 August 2015
Accepted 21 January 2016

KEYWORDS

Gaussian noisy environment; time fractional diffusions; time and space fractional order SPDE; Fox H-functions; fundamental solutions; nonnegativity; heat kernel type estimate; chaos expansion; moment estimates

1. Introduction

In this article we consider the following linear stochastic partial differential equation of fractional orders both in time and space variables:

$$\begin{cases} (\partial^\beta + \frac{\nu}{2}(-\Delta)^{\alpha/2})u(t, x) = \lambda u(t, x)\dot{W}(t, x), & t > 0, x \in \mathbb{R}^d, \\ \frac{\partial^k}{\partial t^k}u(t, x) \Big|_{t=0} = u_k(x), & 0 \leq k \leq \lceil \beta \rceil - 1, x \in \mathbb{R}^d, \end{cases} \quad (1.1)$$

with $\beta \in (1/2, 2)$ and $\alpha \in (0, 2]$, where $\lceil \beta \rceil$ is the smallest integer greater than or equal to β . Here and throughout the paper we denote $\partial^k = \frac{\partial^k}{\partial t^k}$, $k \in \mathbb{N}$. We limit our consideration to the above parameter ranges of β and α since we plan to use some particular properties of the corresponding Fox H-functions which will be proved only for these parameter ranges. Now let us give more detailed explanation on the terms appearing in the above equation.

The fractional derivative in time $\partial^\beta = \frac{\partial^\beta}{\partial t^\beta}$ is understood in the *Caputo* sense:

$$\partial^\beta f(t) := \begin{cases} \frac{1}{\Gamma(m-\beta)} \int_0^t \frac{f^{(m)}(\tau)}{(t-\tau)^{\beta+1-m}} d\tau & \text{if } m-1 < \beta < m, \\ \frac{d^m}{dt^m} f(t) & \text{if } \beta = m, \end{cases}$$

where $t \geq 0$. $\Delta = \sum_{i=1}^d \frac{\partial^2}{\partial x_i^2}$ is the Laplacian with respect to spatial variables and $(-\Delta)^{\alpha/2}$ is the fractional Laplacian. \dot{W} is a zero mean Gaussian noise with the following covariance structure

$$\mathbb{E}(\dot{W}(t, x)\dot{W}(s, y)) = \gamma(t-s)\Lambda(x-y),$$

where both (possibly generalized) functions γ and Λ are assumed to be nonnegative and nonnegative definite. We denote by μ the Fourier transformation measure of $\Lambda(x)$. Namely,

$$\Lambda(x-y) = \frac{1}{(2\pi)^d} \int_{\mathbb{R}^d} e^{i\xi(x-y)} \mu(d\xi).$$

This Fourier transform is understood in distributional sense (see Section 2).

When $\gamma(t) = \delta_0(t)$ and $\Lambda(x) = \delta_0(x)$, this noise \dot{W} reduces to the *space-time white noise*. $\nu > 0$ and λ are some real valued parameters. The given initial conditions $u_k(x)$ are assumed to be continuous and bounded functions. The product $u(t, x)\dot{W}(t, x)$ in Equation (1.1) is the Wick one (see e.g. [20]). So, equation will be understood in the Skorohod sense. Let us point out that some of our results can also be extended to nonlinear equation (namely, replace $u(t, x)\dot{W}(t, x)$ in (1.1) by $\sigma(u(t, x))\dot{W}(t, x)$ for a Lipschitz nonlinear function σ). However, we limit ourselves to this linear case for two reasons: One is to simplify the presentation and to better explain the ideas and the other one is that we want to use the chaos expansion method.

The deterministic counterparts of Equation (1.1) have received a lot of attention and are called anomalous diffusions. They appeared in biological physics and other fields. Equation (1.1) is an anomalous diffusion in a Gaussian noisy environment. More detailed motivations for the study of this type of equations are given in [4,9,17,27]. Here, we briefly mention some recent results.

When $\beta \in \{1, 2\}$ is an integer, $\alpha = 2$, equation has been studied by many authors, see e.g. [1,2,5,6,19]. The work by Chen and Dalang [7] deals with the case where $\beta = 1$, $\alpha \in (1, 2]$. Khoshnevisan and Foondun [13] and Song [34] study a similar equation with the α -stable generator $(-\Delta)^{\alpha/2}$ replaced by a general Lévy generator.

When $\beta \in (0, 1)$, $\alpha = 2$, Δ is replaced by a general elliptic operator, and \dot{W} is a fractional noise, equation was studied in [17].

When $\beta \in (0, 1)$, $\alpha = 2$ and \dot{W} is a fractional noise, the smoothed equation

$$\left(\partial^\beta - \frac{\nu}{2}\Delta\right) u(t, x) = I_t^{1-\beta} [u(t, x)\dot{W}(t, x)]$$

(see (3.19) for a generalization) was studied in [4]. In a series of papers [14,26,27], Nane and his coauthors studied the case $\alpha \in (0, 2]$.

The case $\beta \in (0, 1)$ corresponds to the slow diffusion (subdiffusion). For the fast diffusion case (super diffusion), i.e. $\beta \in (1, 2)$, there have been only a few works.

The first author of this paper studies in [4] the smoothed equation with $\alpha = 2$, $d = 1$ and with space–time white noise. The corresponding non-smoothed equation is studied recently in [8]. Both papers [4,8] deal with the nonlinear equation, i.e. $\rho(u)\dot{W}$ with ρ being a Lipschitz function.

To study Equation (1.1) the important tools that we shall use are the fundamental solutions corresponding to its deterministic counterpart. Let us briefly describe them. There are two fundamental solutions

$$Z(t, x) := Z_{\alpha, \beta, d}(t, x) \quad \text{and} \quad Y(t, x) := Y_{\alpha, \beta, d}(t, x)$$

such that the solution $u(t, x)$ to the following deterministic equation (the deterministic counterpart of (1.1))

$$\begin{cases} \left(\partial^\beta + \frac{\nu}{2} (-\Delta)^{\alpha/2} \right) u(t, x) = f(t, x), & t > 0, x \in \mathbb{R}^d, \\ \left. \frac{\partial^k}{\partial t^k} u(t, x) \right|_{t=0} = u_k(x), & 0 \leq k \leq \lceil \beta \rceil - 1, x \in \mathbb{R}^d, \end{cases} \quad (1.2)$$

is represented by

$$u(t, x) = J_0(t, x) + \int_0^t ds \int_{\mathbb{R}^d} dy f(s, y) Y(t-s, x-y), \quad (1.3)$$

where f is a continuous and bounded function on $\mathbb{R}_+ \times \mathbb{R}^d$, and u_k is a continuous and bounded function on \mathbb{R}^d . In Equation (1.3) and throughout the paper, we denote

$$J_0(t, x) := \sum_{k=0}^{\lceil \beta \rceil - 1} \int_{\mathbb{R}^d} u_{\lceil \beta \rceil - 1 - k}(y) \partial^k Z(t, x-y) dy. \quad (1.4)$$

Equations (1.3) and (1.4) say that Z and Y are the fundamental solutions corresponding respectively to the initial conditions and the inhomogeneous term of Equation (1.2). For some parameter ranges of α and β , the fundamental solutions have been studied in [12,24,31,33]. In Section 3.1 we shall study them for all $\beta \in (1/2, 2)$ and $\alpha \in (0, 2]$. In particular, we shall obtain some new properties such as the positivity of the fundamental solutions Y and Z .

Equation (1.3) motivates us to study the mild solution to (1.1) (see e.g. Definition 2.1 below), namely, the solution to the following stochastic integral equation:

$$u(t, x) = J_0(t, x) + \int_0^t \int_{\mathbb{R}^d} Y(t-s, x-y) u(s, y) W(ds, dy). \quad (1.5)$$

As in the classical case, the above equation can be studied by using the Itô–Wiener chaos expansion. To this end we need to understand well the two fundamental solutions Z and Y . In particular, we need their nonnegativity and some heat kernel like estimates.

The nonnegativity of some Z 's is known. However, since Y is the *Riemann–Liouville* fractional derivative of Z , its nonnegativity is a challenging problem. There have been only few results: As proved in Lemma 25 of [31], $Y_{2,\beta,d}$ with $\beta \in (1, 2)$ is nonnegative if and only if $d \leq 3$. The one dimensional case is proved in [25], namely, $D_t Z_{\alpha,\beta,1}$, and hence $Y_{\alpha,\beta,1}$ is nonnegative either if $1 < \beta \leq \alpha \leq 2$, or if $\alpha \in (0, 1]$ and $\beta \in (0, 2)$. In this paper, we shall show the nonnegativity of Y in the following three cases:

$$\begin{cases} \alpha \in (0, 2], \beta \in (1/2, 1), d \in \mathbb{N}, \\ \alpha \in (0, 2], \beta \in (1, \alpha), d = 1, \\ \alpha = 2, \beta \in (1, 2), d = 2, 3. \end{cases} \quad (1.6)$$

This includes the above mentioned results as special cases. Let us also point out that for the smoothed SPDE, only the fundamental solution Z is needed, which is usually more regular than the fundamental solution Y .

When $\beta = 1$ and $\alpha = 2$, to show the solution of (1.1) is square integrable, it is assumed in [18,19] that the covariance of noise satisfies the following conditions:

- (i) γ is locally integrable;
- (ii) Dalang's condition $\int_{\mathbb{R}^d} \frac{\mu(d\xi)}{1 + |\xi|^2} < \infty$ is satisfied (see also [10,13]).

For the existence and uniqueness of the solution to the general Equation (1.1), Dalang's condition will be replaced by the following condition:

$$\int_{\mathbb{R}^d} \frac{\mu(d\xi)}{1 + |\xi|^{2\alpha - \alpha/\beta}} < \infty. \quad (1.7)$$

It is obvious that if it is formally set $\alpha = 2$ and $\beta = 1$, then (1.7) is reduced to the usual Dalang's condition.

The remaining part of the paper is organized as follows. We first specify the noise structure and present the definition of the solution in Section 2. The main results are Theorem 3.5 on the existence and uniqueness of the mild solution and Theorem 3.11 on the moment bounds of the solution stated in Section 3. The proof of these two theorems are based on some properties of the fundamental solutions represented in terms of the Fox H-functions. These results themselves are of particular interest and importance. We also list them as Theorems 3.1 and 3.3 in Section 3. The properties of the fundamental solutions (Theorem 3.1) are proved in Section 4.1 by using the Fox H-functions. In Section 4.2, we obtain an expression of the density function for the d -dimensional spherically symmetric α -stable distribution – an auxiliary result (Theorem 3.3) which is used in the proof of Theorem 3.1. The existence and uniqueness result (Theorem 3.5) of the solution to (1.1) is proved in Section 5. In Section 6, we prove the explicit moment bounds when Λ is the Riesz kernel.

Our main results (Theorem 3.5) assume that the fundamental solutions are nonnegative. However, when $1 < \beta < 2$ and when the dimension is high, the nonnegativity of the fundamental solution Y is not known yet. In this case, we shall show in Theorem 3.14 the existence and uniqueness of the solution of (1.1) for some specific Gaussian noise whose covariance function Λ is the Riesz kernel. Finally, in Appendix 1 we collect some knowledge on the Fox H-function which we need in this paper.

2. Preliminary

Let us start by introducing some basic notions on Fourier transforms. The space of real-valued infinitely differentiable functions on \mathbb{R}^d with compact support is denoted by $\mathcal{D}(\mathbb{R}^d)$ or \mathcal{D} . The space of Schwartz functions is denoted by $\mathcal{S}(\mathbb{R}^d)$ or \mathcal{S} . Its dual, the space of tempered distributions, is denoted by $\mathcal{S}'(\mathbb{R}^d)$ or \mathcal{S}' . The Fourier transform is defined with the normalization

$$\mathcal{F}u(\xi) = \int_{\mathbb{R}^d} e^{-i\xi \cdot x} u(x) dx,$$

so that the inverse Fourier transform is given by $\mathcal{F}^{-1}u(\xi) = (2\pi)^{-d} \mathcal{F}u(-\xi)$.

Similarly to [19], on a complete probability space (Ω, \mathcal{F}, P) we consider a Gaussian noise W encoded by a centered Gaussian family $\{W(\varphi); \varphi \in \mathcal{D}(\mathbb{R}_+ \times \mathbb{R}^d)\}$, whose covariance structure is given by

$$\mathbb{E}(W(\varphi)W(\psi)) = \int_{\mathbb{R}_+^2 \times \mathbb{R}^{2d}} \varphi(s, x)\psi(t, y)\gamma(s-t)\Lambda(x-y) dx dy ds dt, \quad (2.1)$$

where $\gamma: \mathbb{R} \rightarrow \mathbb{R}_+$ and $\Lambda: \mathbb{R}^d \rightarrow \mathbb{R}_+$ are nonnegative definite functions and the Fourier transform $\mathcal{F}\Lambda = \mu$ such that $\mu(d\xi)$ is a tempered measure, that is, there is an integer $m \geq 1$ such that $\int_{\mathbb{R}^d} (1 + |\xi|^2)^{-m} \mu(d\xi) < \infty$. Throughout the paper, we assume that γ is locally integrable and we denote

$$C_t := 2 \int_0^t \gamma(s) ds, \quad t > 0. \quad (2.2)$$

Let \mathcal{H} be the completion of $\mathcal{D}(\mathbb{R}_+ \times \mathbb{R}^d)$ endowed with the inner product

$$\begin{aligned} \langle \varphi, \psi \rangle_{\mathcal{H}} &= \int_{\mathbb{R}_+^2 \times \mathbb{R}^{2d}} \varphi(s, x)\psi(t, y)\gamma(s-t)\Lambda(x-y) dx dy ds dt \\ &= \frac{1}{(2\pi)^d} \int_{\mathbb{R}_+^2 \times \mathbb{R}^d} \mathcal{F}\varphi(s, \xi)\overline{\mathcal{F}\psi(t, \xi)}\gamma(s-t)\mu(d\xi) ds dt, \end{aligned} \quad (2.3)$$

where $\mathcal{F}\varphi$ refers to the Fourier transform with respect to the space variable only. The mapping $\varphi \rightarrow W(\varphi)$ defined on $\mathcal{D}(\mathbb{R}_+ \times \mathbb{R}^d)$ can be extended to a linear isometry between \mathcal{H} and the Gaussian space spanned by W . We will denote this isometry by

$$W(\phi) = \int_0^\infty \int_{\mathbb{R}^d} \phi(t, x) W(dt, dx), \quad \text{for } \phi \in \mathcal{H}.$$

Notice that if ϕ and ψ are in \mathcal{H} , then $\mathbb{E}(W(\phi)W(\psi)) = \langle \phi, \psi \rangle_{\mathcal{H}}$.

We will denote by D the derivative operator in the sense of Malliavin calculus. That is, if F is a smooth and cylindrical random variable of the form

$$F = f(W(\phi_1), \dots, W(\phi_n)),$$

with $\phi_i \in \mathcal{H}, f \in C_p^\infty(\mathbb{R}^n)$ (namely f and all its partial derivatives have polynomial growth), then DF is the \mathcal{H} -valued random variable defined by

$$DF = \sum_{j=1}^n \frac{\partial f}{\partial x_j}(W(\phi_1), \dots, W(\phi_n))\phi_j.$$

The operator D is closable from $L^2(\Omega)$ into $L^2(\Omega; \mathcal{H})$ and we define the Sobolev space $\mathbb{D}^{1,2}$ as the closure of the space of smooth and cylindrical random variables under the norm

$$\|F\|_{1,2} = \sqrt{\mathbb{E}[F^2] + \mathbb{E}[\|DF\|_{\mathcal{H}}^2]}.$$

We denote by δ the adjoint of the derivative operator given by the duality formula

$$\mathbb{E}(\delta(u)F) = \mathbb{E}(\langle DF, u \rangle_{\mathcal{H}}), \tag{2.4}$$

for all $F \in \mathbb{D}^{1,2}$ and any element $u \in L^2(\Omega; \mathcal{H})$ in the domain of δ . The operator δ is also called the *Skorohod integral* because in the case of the Brownian motion, it coincides with an extension of the Itô integral introduced by Skorohod. We refer to Nualart [28] for a detailed account of the Malliavin calculus with respect to a Gaussian process.

With the Skorohod integral introduced, the definition of the solution to Equation (1.1) can be stated as follows.

Definition 2.1: Let Z and Y be the fundamental solutions defined by (1.2) and (1.3). An adapted random field $\{u = u(t, x) : t \geq 0, x \in \mathbb{R}^d\}$ such that $\mathbb{E}[u^2(t, x)] < +\infty$ for all (t, x) is a *mild solution* to (1.1), if for all $(t, x) \in \mathbb{R}_+ \times \mathbb{R}^d$, the process

$$\left\{ Y(t-s, x-y)u(s, y)1_{[0,t]}(s) : s \geq 0, y \in \mathbb{R}^d \right\}$$

is Skorohod integrable (see (2.4)), and u satisfies

$$u(t, x) = J_0(t, x) + \int_0^t \int_{\mathbb{R}^d} Y(t-s, x-y)u(s, y)W(ds, dy) \tag{2.5}$$

almost surely for all $(t, x) \in \mathbb{R}_+ \times \mathbb{R}^d$, where $J_0(t, x)$ is defined by (1.4).

The main ingredient in proving the existence and uniqueness of the solution is the Wiener chaos expansion, to which we now turn.

Suppose that $u = \{u(t, x); t \geq 0, x \in \mathbb{R}^d\}$ is a square integrable solution to Equation (2.5). Then for all fixed (t, x) the random variable $u(t, x)$ admits the following Wiener chaos expansion

$$u(t, x) = \sum_{n=0}^{\infty} I_n(f_n(\cdot, \cdot, t, x)), \tag{2.6}$$

where for each (t, x) , $f_n(\cdot, \cdot, t, x)$ is a symmetric element in $\mathcal{H}^{\otimes n}$. Then, as in [15–17], to show the existence and uniqueness of the solution it suffices to show that for all (t, x) we have

$$\sum_{n=0}^{\infty} n! \|f_n(\cdot, \cdot, t, x)\|_{\mathcal{H}^{\otimes n}}^2 < \infty. \tag{2.7}$$

For technical reasons (see (2.8) below), we will assume, throughout the paper, the following properties on Λ :

- $\Lambda : \mathbb{R}^d \rightarrow [0, \infty]$ is a continuous function, where $[0, \infty]$ is the usual one-point compactification of $[0, \infty)$.
- $\Lambda(x) < \infty$ if and only if $x \neq 0$ or $\mathcal{F}(\Lambda) \in L^\infty(\mathbb{R}^d)$ and $\Lambda(x) < \infty$ when $x \neq 0$.

With these two assumptions, according to Lemma 5.6 in [21], for any Borel probability measures $\nu_1(dx)$ and $\nu_2(dx)$, the following identity holds,

$$\int_{\mathbb{R}^d} \int_{\mathbb{R}^d} \Lambda(x - y) \nu_1(dx) \nu_2(dy) = \frac{1}{(2\pi)^d} \int_{\mathbb{R}^d} \mathcal{F}\nu_1(\xi) \overline{\mathcal{F}\nu_2(\xi)} \mu(d\xi). \tag{2.8}$$

In particular, the above result can be applied to the case when $\nu_1(dx) = f_1(x)dx$ and $\nu_2(dx) = f_2(x)dx$ for two nonnegative functions f_1 and $f_2 \in L^1(\mathbb{R}^d)$.

3. Main results

3.1. Fundamental solutions: formulas and nonnegativity

Our first result is concerned with the fundamental solutions to (1.2) stated in the following theorem. We need the two parameter *Mittag-Leffler function* $E_{\alpha,\beta}(z)$:

$$E_{\alpha,\beta}(z) := \sum_{n=0}^{\infty} \frac{z^n}{\Gamma(\alpha n + \beta)}, \quad \Re(\alpha) > 0, \beta \in \mathbb{C}, z \in \mathbb{C}, \tag{3.1}$$

where $\Re(\alpha)$ is the real part of the complex number α . When $\beta = 1$, we also write $E_\alpha(z) := E_{\alpha,1}(z)$. The H -functions appearing in the following theorem and their properties are given in Appendix 1.

Theorem 3.1: *The fundamental solutions to (1.2) are given by*

$$Z(t, x) := Z_{\alpha,\beta,d}(t, x) = \pi^{-d/2} t^{\lceil\beta\rceil-1} |x|^{-d} H_{2,3}^{2,1} \left(\frac{|x|^\alpha}{2^{\alpha-1} \nu t^\beta} \left| \begin{matrix} (1,1), (\lceil\beta\rceil, \beta) \\ (d/2, \alpha/2), (1,1), (1, \alpha/2) \end{matrix} \right. \right) \tag{3.2}$$

and

$$Y(t, x) := Y_{\alpha,\beta,d}(t, x) = \pi^{-d/2} |x|^{-d} t^{\beta-1} H_{2,3}^{2,1} \left(\frac{|x|^\alpha}{2^{\alpha-1} \nu t^\beta} \left| \begin{matrix} (1,1), (\beta, \beta) \\ (d/2, \alpha/2), (1,1), (1, \alpha/2) \end{matrix} \right. \right). \tag{3.3}$$

If $\beta \in (1, 2)$, then

$$Z^*(t, x) := Z_{\alpha,\beta,d}^*(t, x) = \frac{d}{dt} Z_{\alpha,\beta,d}(t, x) = \pi^{-d/2} |x|^{-d} H_{2,3}^{2,1} \left(\frac{|x|^\alpha}{2^{\alpha-1} \nu t^\beta} \left| \begin{matrix} (1,1), (1, \beta) \\ (d/2, \alpha/2), (1,1), (1, \alpha/2) \end{matrix} \right. \right). \tag{3.4}$$

The Fourier transforms of the fundamental solutions are given by the following:

$$\mathcal{F}Z(t, \cdot)(\xi) = t^{[\beta]-1} E_{\beta, [\beta]}(-2^{-1} \nu t^\beta |\xi|^\alpha), \tag{3.5}$$

$$\mathcal{F}Y(t, \cdot)(\xi) = t^{\beta-1} E_{\beta, \beta}(-2^{-1} \nu t^\beta |\xi|^\alpha), \tag{3.6}$$

$$\mathcal{F}Z^*(t, \cdot)(\xi) = E_\beta(-2^{-1} \nu t^\beta |\xi|^\alpha), \quad \text{if } \beta \in (1, 2); \tag{3.7}$$

Moreover, we have the following results on the positivity of the fundamental solutions.

- (a) If $\beta \in (0, 1]$, $d \in \mathbb{N}$ and $\alpha \in (0, 2]$, then both $Z(t, x)$ and $Y(t, x)$ are nonnegative;
- (b) If $\beta \in (1, 2)$, $d \in \{2, 3\}$, and $\alpha = 2$, then both $Z(t, x)$ and $Y(t, x)$ are nonnegative;
- (c) If $\beta \in (1, 2)$, $d = 1$ and $\alpha \in [\beta, 2]$, then all $Z(t, x)$, $Y(t, x)$ and $Z^*(t, x)$ are nonnegative.

The proof of this theorem is given in Section 4.1.

Remark 3.2: Here are some known special cases:

- (1) When $\alpha = 2$ and $\beta \in (0, 1)$, it is proved in [24,33] and in [12], respectively, that

$$Z_0(t, x) = \pi^{-d/2} |x|^{-d} H_{1,2}^{2,0} \left(\frac{|x|^2}{2\nu t^\beta} \middle| \begin{matrix} (1, \beta) \\ (d/2, 1), (1, 1) \end{matrix} \right), \tag{3.8}$$

and

$$Y_0(t, x) = \pi^{-d/2} |x|^{-d} t^{\beta-1} H_{1,2}^{2,0} \left(\frac{|x|^2}{2\nu t^\beta} \middle| \begin{matrix} (\beta, \beta) \\ (d/2, 1), (1, 1) \end{matrix} \right), \tag{3.9}$$

which correspond to our $Z_{2,\beta,d}(t, x)$ and $Y_{2,\beta,d}(t, x)$, respectively. The equivalence is clear by applying Property 1.3. For $Z_{2,\beta,d}$, see also [23, Chapter 6].

- (2) When $\alpha = 2$ and $\beta \in (0, 2)$, it is proved in [31] that

$$\Gamma_{\beta,d}(t, x) = \pi^{-d/2} |x|^{-d} t^{\beta-1} H_{1,2}^{2,0} \left(\frac{|x|^2}{4t^\beta} \middle| \begin{matrix} (\beta, \beta) \\ (d/2, 1), (1, 1) \end{matrix} \right), \tag{3.10}$$

which corresponds to our $Y_{2,\beta,d}$ with $\nu = 2$.

- (3) In [25], the fundamental solution $Z_{\alpha,\beta,d}^*(t, x)$ has been studied for all $\alpha, \beta \in (0, 2)$ and $d = 1$. From the Mellin–Barnes integral representation (6.6) of [25], we see that the reduced Green function of [25] can be expressed by using the Fox H-function:

$$K_{\alpha,\beta}^\theta(x) = \frac{1}{|x|} H_{3,3}^{2,1} \left(|x|^\alpha \middle| \begin{matrix} (1, 1), (1, \beta), (1, \frac{\alpha-\theta}{2}) \\ (1, 1), (1, \alpha), (1, \frac{\alpha-\theta}{2}) \end{matrix} \right), \quad x \in \mathbb{R}, \tag{3.11}$$

where α and β have the same meaning as in this paper and θ is the skewness: $|\theta| \leq \min(\alpha, 2 - \alpha)$. For the symmetric α -stable case, i.e. $\theta = 0$, this expression can be simplified by using the definition of the Fox H-function and the fact that (see, e.g. [29, 5.5.5])

$$\frac{\Gamma(1 + \alpha s)}{\Gamma(1 + \alpha s/2)} = \frac{1}{\sqrt{\pi}} 2^{\alpha s} \Gamma(1/2 + \alpha s/2). \tag{3.12}$$

Hence,

$$K_{\alpha,\beta}^0(x) = \frac{1}{\sqrt{\pi}|x|} H_{2,3}^{2,1} \left((|x|/2)^\alpha \left| \begin{matrix} (1,1), (1,\beta) \\ (1/2,\alpha/2), (1,1), (1,\alpha/2) \end{matrix} \right. \right), \quad x \in \mathbb{R}. \quad (3.13)$$

This implies that the fundamental solution in [25, (1.3)]

$$G_{\alpha,\beta}^0(x, t) = t^{-\beta/\alpha} K_{\alpha,\beta}^0(t^{-\beta/\alpha}x) = \frac{1}{\sqrt{\pi}|x|} H_{2,3}^{2,1} \left(\frac{|x|^\alpha}{2^\alpha t^\beta} \left| \begin{matrix} (1,1), (1,\beta) \\ (1/2,\alpha/2), (1,1), (1,\alpha/2) \end{matrix} \right. \right)$$

corresponds to our $Z_{\alpha,\beta,1}^*(t, x)$ with $\nu = 2$.

The proof of the nonnegativity part in Theorem 3.1 requires a representation of the spherically symmetric α -stable distribution from the Fox H-function, which is of interest by itself. The one-dimensional case can be found in [25]; see Remark 3.4 below.

Theorem 3.3: *Let X be a centered, d -dimensional spherically symmetric α -stable random variable with $\alpha \in (0, 2]$. Then the characteristic function and the density of X are, respectively,*

$$f_{\alpha,d}(\xi) = \exp(-|\xi|^\alpha), \quad \xi \in \mathbb{R}^d, \quad (3.14)$$

and

$$\rho_{\alpha,d}(x) = \pi^{-d/2} |x|^{-d} H_{1,2}^{1,1} \left((|x|/2)^\alpha \left| \begin{matrix} (1,1) \\ (d/2,\alpha/2), (1,\alpha/2) \end{matrix} \right. \right), \quad x \in \mathbb{R}^d. \quad (3.15)$$

The proof of this theorem is given in Section 4.2.

Remark 3.4: When $d = 1$, the formula (3.15) yields a result in [25]. In particular, as proved in [25] (see (3.11)), when $d = 1$, we have

$$\rho_{\alpha,1}(x) = |x|^{-1} H_{2,2}^{1,1} \left(|x|^\alpha \left| \begin{matrix} (1,1), (1,\alpha/2) \\ (1,\alpha), (1,\alpha/2) \end{matrix} \right. \right) = \pi^{-1/2} |x|^{-1} H_{1,2}^{1,1} \left((|x|/2)^\alpha \left| \begin{matrix} (1,1) \\ (1/2,\alpha/2), (1,\alpha/2) \end{matrix} \right. \right),$$

where the second equality is due to (3.12) and the definition of the Fox H-function.

3.2. Existence and uniqueness of solutions to the SPDE

The following is one of the main theorems of the paper.

Theorem 3.5: *Assume the following conditions:*

- (1) $Y_{\alpha,\beta,d}(t, x)$ is nonnegative;
- (2) $\beta \in (1/2, 2)$ and $\alpha \in (0, 2]$;
- (3) γ is locally integrable;
- (4) μ satisfies Dalang's condition (1.7);
- (5) The initial conditions are such that for all $t > 0$,

$$\widehat{C}_t := \sup_{y \in \mathbb{R}^d, s \in [0,t]} |J_0(s, y)| < +\infty. \quad (3.16)$$

Then relation (2.7) holds for each (t, x) . Consequently, Equation (1.1) admits a unique mild solution in the sense of Definition 2.1.

The proof of this theorem is given in Section 5.

Remark 3.6: From Theorem 3.1, it follows that the three cases in (1.6) satisfy the above assumptions (1) and (2). Moreover, if $u_k \in L^\infty(\mathbb{R}^d)$ for the first two cases in (1.6), or if $u_0 \in L^\infty(\mathbb{R}^d)$ and $u_1(x) \equiv u_1$ is a constant for the last case in (1.6), then by Lemma 6.1 below,

$$|J_0(t, x)| \leq \|u_0\|_{L^\infty(\mathbb{R}^d)} + t^{\beta-1} \|u_1\|_{L^\infty(\mathbb{R}^d)} 1_{\{\beta>1\}}.$$

Hence the assumption (5) is also satisfied. The Dalang condition (1.7) imposes a further restriction on the possible values of (α, β) due to the spatial correlation $\Lambda(x)$.

Remark 3.7: Space–time white noise case When the noise \dot{W} is a space–time white noise, i.e. $\gamma(t) = \delta_0(t)$ and $\Lambda(x) = \delta_0(x)$, then Dalang’s condition (1.7) becomes

$$\frac{d}{\alpha} + \frac{1}{\beta} < 2. \tag{3.17}$$

This condition implies that $\beta > 1/2$. In particular, if $\alpha = 2$ and $d = 1$, then (3.17) reduces to

$$\beta > 2/3,$$

which recovers the condition in [8] and [9, Section 5.2]. If $\beta = 1$ and $d = 1$, then this condition becomes

$$\alpha > 1, \tag{3.18}$$

which recovers the condition in [7].

3.3. The smoothed equation

The methodology used in the proof of Theorem 3.5 can also be used to study the following equation

$$\left(\partial^\beta + \frac{\nu}{2}(-\Delta)^{\frac{\alpha}{2}}\right) u(t, x) = I_t^{[\beta]-\beta} [u(t, x) \dot{W}(t, x)], \tag{3.19}$$

with the same initial conditions as (1.1). Here I_t^β is the Riemann–Liouville fractional integral of order β (with an abuse of the notation β):

$$I_t^\beta f(t) = \frac{1}{\Gamma(\beta)} \int_0^t (t-s)^{\beta-1} f(s) ds, \quad \text{for } t > 0 \text{ and } \beta > 0.$$

Due to the fractional integral in Equation (3.19) which plays a smoothing role, the mild formulation for the solution can be expressed by using $Z(t, x)$ only, namely,

$$u(t, x) = J_0(t, x) + \int_0^t \int_{\mathbb{R}^d} Z(t-s, x-y) u(s, y) W(ds, dy). \tag{3.20}$$

Then, using the same procedure as in the proof of Theorem 3.5, we have the following result.

Theorem 3.8: Assume the conditions (3) and (5) in Theorem 3.5 and the other conditions are replaced by the following:

- (1') $Z_{\alpha,\beta,d}(t, x)$ is nonnegative;
- (2') $\beta \in (1/2, 1] \cup (3/2, 2)$ and $\alpha \in (0, 2]$;
- (3') μ satisfies

$$\int_{\mathbb{R}^d} \frac{\mu(d\xi)}{1 + |\xi|^{\alpha(2\lceil\beta\rceil-1)/\beta}} < \infty. \tag{3.21}$$

Then relation (2.7) holds for each (t, x) . Consequently, the smoothed Equation (3.19) admits a unique mild solution in the sense of Definition 2.1 with Y replaced by Z .

Remark 3.9: The condition (1') is different and is usually easier to verify than the condition (1) in Theorem 3.5. When $\beta \in (1/2, 1]$, the condition (3.21) becomes $\int_{\mathbb{R}^d} \frac{\mu(d\xi)}{1+|\xi|^{\alpha/\beta}} < \infty$ which is also weaker than (1.7) (since $\beta \leq 1$). When $\beta \in (3/2, 2)$, the condition (3.21) becomes $\int_{\mathbb{R}^d} \frac{\mu(d\xi)}{1+|\xi|^{3\alpha/\beta}} < \infty$ which is also weaker than (1.7) (since $\beta < 2$).

The proof is essentially the same as that for Theorem 3.5, the only change in the proof worthy to be pointed out is that instead of computing the integral

$$\int_0^\infty w^{2(\lceil\beta\rceil-1)} E_{\beta,\lceil\beta\rceil}^2(-2^{-1}vw^\beta|\xi|^\alpha)dw,$$

we now need to compute the integral

$$\begin{aligned} & \int_0^\infty w^{2(\lceil\beta\rceil-1)} E_{\beta,\lceil\beta\rceil}^2(-2^{-1}vw^\beta|\xi|^\alpha)dw \\ &= \frac{(2/v)^{(2\lceil\beta\rceil-1)/\beta}}{|\xi|^{\alpha(2\lceil\beta\rceil-1)/\beta}} \int_0^\infty \frac{1}{\beta} s^{\frac{1}{\beta}(2\lceil\beta\rceil-\beta-1)} E_{\beta,\lceil\beta\rceil}^2(-vs)ds \\ &= \frac{C}{|\xi|^{\alpha(2\lceil\beta\rceil-1)/\beta}}. \end{aligned} \tag{3.22}$$

The integrability condition of the above equation at zero and at infinity implies that $\beta > 0$ and $\beta \in (1/2, 1] \cup (3/2, 2]$ (which is equivalent to $\lceil\beta\rceil < \beta + 1/2$), respectively. Note that this condition on β is more restrictive than the condition $\beta \in (0, 2)$ in [4].

Remark 3.10: (Space–time white noise case) When the noise \dot{W} is a space–time white noise (namely $\mu(d\xi) = d\xi$), then Dalang’s condition (3.21) becomes

$$d < \alpha(2\lceil\beta\rceil - 1)/\beta \quad \text{or} \quad \frac{d}{\alpha} + \frac{1}{\beta} < \frac{2\lceil\beta\rceil}{\beta}. \tag{3.23}$$

In particular, if $\alpha = 2$ and $d = 1$, then this condition reduces to $\beta < 2$. If $\beta = 1$ and $d = 1$, then this condition becomes (3.18), which recovers the condition in [7].

3.4. Moment bounds

In this subsection we give some upper bounds for the p -th moment and the lower bound of the second moment of the solution for some specific choice of the covariance kernel.

Theorem 3.11: Assume the following conditions:

- (1) The initial conditions satisfy condition (5) of Theorem 3.5;
- (2) (α, β, d) satisfies one of the three conditions in (1.6);

(3) $\Lambda(x) = |x|^{-\kappa}, x \in \mathbb{R}^d$ with

$$0 < \kappa < \min(2\alpha - \alpha/\beta, d).$$

Then the solution $u(t, x)$ to (1.1) satisfies that for all $p \geq 1$,

$$\mathbb{E}[|u(t, x)|^p] \leq C^p \widehat{C}_t^p \exp\left(t(C_\kappa C_t \widetilde{C} C_* (2/\nu)^{\kappa/\alpha} (2\pi)^{-d})^{\frac{\alpha}{2\alpha\beta - \alpha - \beta\kappa}} p^{\frac{2\alpha\beta - \beta\kappa}{2\alpha\beta - \alpha - \beta\kappa}}\right), \quad (3.24)$$

where C_t and \widehat{C}_t are defined in (2.2) and (3.16), respectively, $C = C(\alpha, \beta, \kappa) > 0$, and

$$C_* = \Gamma(2\beta - 1 - \beta\kappa/\alpha) \quad \text{and} \quad \widetilde{C} = \int_{\mathbb{R}^d} E_{\beta, \beta}^2(-|\xi|^\alpha) |\xi|^{\kappa-d} d\xi,$$

and C_κ appears in the Fourier transform of $|x|^{-\kappa}$, i.e. $\mu(d\xi) = C_\kappa |\xi|^{\kappa-d}$.

In particular, if γ is the Dirac delta function and if the initial data $u_0(x) \equiv u_0 > 0$ is a constant and $u_1 \equiv 0$ when $\beta > 1$, then for some constant $c = c(\alpha, \beta, \kappa) > 0$,

$$\mathbb{E}[|u(t, x)|^2] \geq c u_0^2 \exp\left(t(C_\kappa \widetilde{C} (4\pi)^{-d} C_* (2/\nu)^{\kappa/\alpha})^{\frac{1}{2\beta - 1 - \beta\kappa/\alpha}}\right). \quad (3.25)$$

The proof of this theorem is given in Section 6. The same method can be used to obtain the moment bound for the solution to the smoothed Equation (3.19).

Remark 3.12: When $\beta = 1$ and $\alpha = 2$, Equation (1.1) is reduced to the multiplicative stochastic heat Equation (1.1) considered in [19]. In this case the exponent of p in (3.24) becomes

$$\frac{2\alpha\beta - \beta\kappa}{2\alpha\beta - \alpha - \beta\kappa} = \frac{4 - \kappa}{2 - \kappa},$$

which is the same as in [19, Theorem 6.1, inequality (6.1)] (with $\kappa = a$). If we assume $\gamma(t) = t^{-\tilde{\beta}}$, then $C_t = C t^{-\tilde{\beta}+1}$. The exponent of t in (3.24) is

$$1 + (-\tilde{\beta} + 1) \left(\frac{\alpha}{2\alpha\beta - \alpha - \beta\kappa}\right) = \frac{4 - 2\tilde{\beta} - \kappa}{2 - \kappa},$$

which is the same exponent of t as in [19], inequality (6.1). Hence, we conjecture that the bound (3.24) is sharp.

Theorem 3.13: Assume the conditions (1) and (2) of Theorem 3.11, and assume

(3') $\Lambda(x) = |x|^{-\kappa}, x \in \mathbb{R}^d$ with

$$0 < \kappa < \min(\alpha/\beta, d).$$

Then the solution $u(t, x)$ to the smoothed equation (3.19) satisfies that for all $p \geq 1$,

$$\mathbb{E}[|u(t, x)|^p] \leq C^p \widehat{C}_t^p \exp\left(t[C_\kappa C_t \bar{C} C_\# (2/\nu)^{\kappa/\alpha}]^{\frac{\alpha}{2\alpha|\beta| - \alpha - \beta\kappa}} p^{\frac{2\alpha|\beta| - \beta\kappa}{2\alpha|\beta| - \alpha - \beta\kappa}}\right), \quad (3.26)$$

where $C = C(\alpha, \beta, \kappa) > 0$, \widehat{C}_t is defined in (3.16),

$$C_{\#} = \Gamma(2 \lceil \beta \rceil - 1 - \beta\kappa/\alpha) \quad \text{and} \quad \bar{C} = \int_{\mathbb{R}^d} E_{\beta, \lceil \beta \rceil}(-|\eta|^\alpha) |\eta|^{\kappa-d} d\eta,$$

and C_κ is as defined in Theorem 3.11. In particular, if γ is the Dirac delta function and if the initial data $u_0(x) \equiv u_0 > 0$ is a constant and $u_1 \equiv 0$ when $\beta > 1$, then for some constant $c = c(\alpha, \beta, \kappa) > 0$,

$$\mathbb{E} [|u(t, x)|^2] \geq c u_0^2 \exp \left(t \left[C_\kappa \bar{C} (4\pi)^{-d} C_{\#} (2/\nu)^{\kappa/\alpha} \right]^{\frac{1}{2\beta-1-\beta\kappa/\alpha}} \right). \quad (3.27)$$

The proof of this theorem is a line-by-line change of the proof of Theorem 3.11, and we leave it to the interested reader.

3.5. Case $1 < \beta < 2$ and $d \geq 2$

When $1 < \beta < 2$ and $\alpha \neq 2$, we could not show the nonnegativity of $Y(t, x)$ for high dimension ($d \geq 2$) (see Theorem 3.1 (b)). However, with a slightly different approach, it is possible to obtain similar results to Theorem 3.5 for the Riesz kernel case.

Theorem 3.14: Assume the conditions (2), (3) and (5) of Theorem 3.5, and assume

$$(4') \quad \Lambda(x) = |x|^{-\kappa}, \quad x \in \mathbb{R}^d \text{ with}$$

$$0 < \kappa < \min(2\alpha - \alpha/\beta, d).$$

Then relation (2.7) holds for each (t, x) . Consequently, Equation (1.1) admits a unique mild solution in the sense of Definition 2.1.

This theorem is proved in Section 7.

Remark 3.15: It is easy to see that the condition $\Lambda(x) = |x|^{-\kappa}$ with $0 < \kappa < 2\alpha - \alpha/\beta$ implies Dalang’s condition (1.7). Condition $\kappa < d$ is to guarantee that Λ is a positive function.

4. Fox H-functions: some proofs

4.1. Proof of Theorem 3.1

The proof of Theorem 3.1 will be based on following lemmas.

Lemma 4.1: The function $Z_{\alpha, \beta, d}(t, x)$ has the Fourier transform given by (3.5).

Proof: The proof needs relation (A19) between the Mittag–Leffler function and the Fox H-function. We first note some special cases. The case where $\beta \in (0, 1]$, $\alpha = 2$ and $d \in \mathbb{N}$ can be found in [24, Section 4] or [33]. For $\beta \in (0, 1]$ and for general α , one can simply replace $|\xi|^2$ by $|\xi|^\alpha$ in the argument of [24, Section 4] and then use (A19) to obtain (3.5). The case where $d = 1$, $\beta \in (0, 2)$, and $\alpha \in (0, 2)$ is proved by [25]. For the general case, $Z_{\alpha, \beta, d}$ solves

$$\begin{cases} \left(\partial^\beta + \frac{\nu}{2} (-\Delta)^{\alpha/2} \right) u(t, x) = 0, & t > 0, x \in \mathbb{R}, \\ u(0, x) = \delta_0(x), & \text{if } m \in (0, 1), \\ u(0, x) = 0, \quad \frac{\partial}{\partial t} u(t, x) \Big|_{t=0} = \delta_0(x), & \text{if } m \in [1, 2). \end{cases}$$

Hence, the Fourier transform of $Z_{\alpha, \beta, d}$ satisfies

$$\partial^\beta \mathcal{F}Z(t, \cdot)(\xi) = -\frac{\nu}{2} |\xi|^\alpha \mathcal{F}Z(t, \cdot)(\xi), \quad \frac{\partial^m}{\partial t^m} \mathcal{F}Z(t, \cdot)(\xi) \Big|_{t=0} = 1.$$

This equation can be solved explicitly (see, e.g. [11, Theorem 7.2, on p. 135]) as

$$\mathcal{F}Z(t, \cdot)(\xi) = I_t^m E_\beta(-\nu |\xi|^\alpha t^\beta / 2),$$

which gives immediately (3.5) when $m = 0$. When $m = 1$, the integral can be evaluated by [30, (1.99)] to give

$$\mathcal{F}Z(t, \cdot)(\xi) = t E_{\beta, 2}(-\nu |\xi|^2 t^\beta / 2).$$

This completes the proof of Lemma 4.1. □

Lemma 4.2: *The function $Z_{\alpha, \beta, d}(t, x)$ can be expressed in (3.2).*

Proof: Following Lemma 4.1, we need to compute the inverse Fourier transform of (3.5). Instead of finding the inverse Fourier transform, it turns out that it is easier to verify that the Fourier transform of (3.2) is equal to the right hand side of (3.5). Let now Z be defined by (3.2).

Case I $d = 1$. Notice that $x \mapsto Z(t, x)$ is an even function. We have that

$$\mathcal{F}Z(t, \cdot)(\xi) = 2\pi^{-1/2} t^{\lceil \beta \rceil - 1} \int_0^\infty dx x^{-1} H_{2,3}^{2,1} \left(\frac{x^\alpha}{2^{\alpha-1} \nu t^\beta} \mid \begin{matrix} (1,1), (\lceil \beta \rceil, \beta) \\ (1/2, \alpha/2), (1,1), (1, \alpha/2) \end{matrix} \right) \cos(x\xi).$$

Write the $\cos(\cdot)$ function in the Fox H-function form by (A20) and then apply Property 1.5 to both Fox H-functions and Property 1.4 to the Fox H-function coming from $\cos(\cdot)$:

$$\begin{aligned} \mathcal{F}Z_{\alpha, \beta}(t, \cdot)(\xi) &= \alpha^{-1} t^{\lceil \beta \rceil - 1} \int_0^\infty \frac{dx}{x} H_{2,3}^{2,1} \left(\frac{x}{2^{1-1/\alpha} \nu^{1/\alpha} t^{\beta/\alpha}} \mid \begin{matrix} (1,1/\alpha), (\lceil \beta \rceil, \beta/\alpha) \\ (1/2, 1/2), (1,1/\alpha), (1,1/2) \end{matrix} \right) \\ &\quad \times H_{2,0}^{0,1} \left(\frac{2}{x|\xi|} \mid \begin{matrix} (1,1/2), (1/2, 1/2) \end{matrix} \right). \end{aligned}$$

Now we will apply Theorem 1.8. Notice that both condition (1): $a_1^* = (2 - \beta)/\alpha > 0$, $a_2^* = 0$, $\Delta_2 = -1 \neq 0$, and condition (A16):

$$A_1 = 0, \quad A_2 = \infty, \quad B_1 = \min(1, \alpha), \quad B_2 = 0,$$

of Theorem 1.8 hold. Hence, Theorem 1.8 implies that

$$\mathcal{F}Z(t, \cdot)(\xi) = \alpha^{-1} t^{\lceil \beta \rceil - 1} H_{4,3}^{2,2} \left(\frac{1}{2^{-1/\alpha} \nu^{1/\alpha} t^{\beta/\alpha}} \mid \begin{matrix} (1,1/\alpha), (1,1/2), (1/2, 1/2), (\lceil \beta \rceil, \beta/\alpha) \\ (1/2, 1/2), (1,1/\alpha), (1,1/2) \end{matrix} \right).$$

Then apply Properties 1.5 and 1.3 to simplify the above expression:

$$\begin{aligned} \mathcal{FZ}(t, \cdot)(\xi) &= t^{\lceil\beta\rceil-1} H_{4,3}^{2,2} \left(2 (vt^\beta |\xi|^\alpha)^{-1} \left| \begin{matrix} (1,1), (1,\alpha/2), (1/2,\alpha/2), (\lceil\beta\rceil,\beta) \\ (1/2,\alpha/2), (1,1), (1,\alpha/2) \end{matrix} \right. \right) \\ &= t^{\lceil\beta\rceil-1} H_{1,2}^{1,1} \left(2^{-1} vt^\beta |\xi|^\alpha \left| \begin{matrix} (0,1) \\ (0,1), (1-\lceil\beta\rceil,\beta) \end{matrix} \right. \right). \end{aligned}$$

This proves the lemma when $d = 1$.

Case II $d \geq 2$. Because the function $x \mapsto Z_{\alpha,\beta,d}(t, x)$ is a radial function, it is known that (see, e.g. [36, Theorem 3.3 on p. 155]),

$$\mathcal{FZ}(t, \cdot)(\xi) = 2^{d/2} t^{\lceil\beta\rceil-1} |\xi| \int_0^\infty dx H_{2,3}^{2,1} \left(\frac{x^\alpha}{2^{\alpha-1} vt^\beta} \left| \begin{matrix} (1,1), (\lceil\beta\rceil,\beta) \\ (1/2,\alpha/2), (1,1), (1,\alpha/2) \end{matrix} \right. \right) J_{(d-2)/2}(x|\xi|) (|\xi|x)^{-d/2},$$

where $J_\nu(x)$ is the Bessel function of the first kind. Then we can apply Theorem 1.10.

Similar to the previous case, all conditions are satisfied with the condition $a^* = 2 - \beta > 0$. Hence,

$$\begin{aligned} \mathcal{FZ}(t, \cdot)(\xi) &= t^{\lceil\beta\rceil-1} H_{4,3}^{2,2} \left(2 (vt^\beta |\xi|^\alpha)^{-1} \left| \begin{matrix} (1,1), (1,\alpha/2), (d/2,\alpha/2), (\lceil\beta\rceil,\beta) \\ (d/2,\alpha/2), (1,1), (1,\alpha/2) \end{matrix} \right. \right) \\ &= t^{\lceil\beta\rceil-1} H_{1,2}^{1,1} \left(2^{-1} vt^\beta |\xi|^\alpha \left| \begin{matrix} (0,1) \\ (0,1), (1-\lceil\beta\rceil,\beta) \end{matrix} \right. \right), \end{aligned}$$

where the second equality is due to Property 1.3. This completes the proof of Lemma 4.2. □

Note that the case $d \geq 2$ can be also proved by writing the Bessel function in the Fox H-function form by (A21) and then applying Theorem 1.8. We leave the details for interested readers.

Lemma 4.3: *The fundamental solutions $Y_{\alpha,\beta,d}(t, x)$ and $Z_{\alpha,\beta,d}^*(t, x)$ are given by (3.3) and (3.4), respectively.*

Proof: We first prove the expression for $Y_{\alpha,\beta,d}$. By Section 2 of [12], we know that $Y_{\alpha,\beta,d}(t, x)$ is the Riemann–Liouville fractional derivative in t of $Z_{\alpha,\beta,d}(t, x)$ of order $\lceil\beta\rceil - \beta$. Notice that $Z_{\alpha,\beta,d}(0, x) = 0$ for $|x| \neq 0$. Denote the Riemann–Liouville derivative of order $\beta \in (0, 1)$ by D_{0+}^β , i.e.

$$\left(D_{0+}^\beta f \right) (t) = \frac{d}{dt} \frac{1}{\Gamma(1-\beta)} \int_0^t \frac{f(x)}{(t-x)^\beta} dx, \quad \text{for } t > 0. \tag{4.1}$$

By Property 1.4,

$$Z_{\alpha,\beta,d}(t, x) = \pi^{-d/2} t^{\lceil\beta\rceil-1} |x|^{-d} H_{3,2}^{1,2} \left(\frac{2^{\alpha-1} vt^\beta}{|x|^\alpha} \left| \begin{matrix} (1-d/2,\alpha/2), (0,1), (0,\alpha/2) \\ (0,1), (1-\lceil\beta\rceil,\beta) \end{matrix} \right. \right).$$

Because $a^* = (2 - \beta) + (2 - \alpha)/2 > 0$, we can apply Theorem 1.11,

$$D_{0+}^{\lceil\beta\rceil-\beta} Z_{\alpha,\beta,d}(t, x) = \pi^{-d/2} |x|^{-d} t^{\beta-1} H_{4,3}^{1,3} \left(\frac{2^{\alpha-1} vt^\beta}{|x|^\alpha} \left| \begin{matrix} (1-\lceil\beta\rceil,\beta), (1-d/2,\alpha/2), (0,1), (0,\alpha/2) \\ (0,1), (1-\lceil\beta\rceil,\beta), (1-\beta,\beta) \end{matrix} \right. \right).$$

Then we use Properties 1.3 and 1.5 to simplify the above expression to obtain (3.3). The expression for $Z_{\alpha,\beta,d}^*$ can be proved in a similar way. □

Lemma 4.4: *The Fourier transforms of $Y_{\alpha,\beta,d}(t, x)$ and $Z_{\alpha,\beta,d}^*(t, x)$ are given by (3.6) and (3.7), respectively.*

Proof: We first consider $Y_{\alpha,\beta,d}$. From Lemma 4.1 and the proof of Lemma 4.3 it follows

$$\mathcal{F}Y_{\alpha,\beta,d}(t, \cdot)(\xi) = D_{0+}^{[\beta]-\beta} t^{[\beta]-1} H_{1,2}^{1,1} \left(2^{-1} \nu t^\beta |\xi|^\alpha \mid \begin{matrix} (0,1) \\ (0,1), (1-[\beta],\beta) \end{matrix} \right).$$

Because $a^* = 2 - \beta > 0$, we can apply Theorem 1.11 to obtain that

$$\mathcal{F}Y_{\alpha,\beta,d}(t, \cdot)(\xi) = t^{\beta-1} H_{2,3}^{1,2} \left(2^{-1} \nu t^\beta |\xi|^\alpha \mid \begin{matrix} (1-[\beta],\beta), (0,1) \\ (0,1), (1-[\beta],\beta), (1-\beta,\beta) \end{matrix} \right).$$

This is simplified to (3.6) by Properties 1.3 and 1.5. The identity (3.7) can be obtained in a similar way. □

Lemma 4.5: *For all $\mu > 0$ and $0 < \theta < \min(1, \mu)$, the following H-function is nonnegative:*

$$H_{1,1}^{1,0} \left(|x| \mid \begin{matrix} (\mu,\theta) \\ (1,1) \end{matrix} \right) \geq 0, \quad \text{for all } x \in \mathbb{R}. \tag{4.2}$$

Proof: We only need to prove that the following function is nonnegative

$$f(x) = |x|^{-1} H_{1,1}^{1,0} \left(|x| \mid \begin{matrix} (\mu,\theta) \\ (1,1) \end{matrix} \right), \quad x \in \mathbb{R}.$$

By Theorem 1.9 and Equation (A19), the Laplace transform of f is equal to

$$\int_0^\infty dx e^{-xz} f(x) = E_{\theta,\mu}(-z).$$

By [32], we know that the above Mittag–Leffler function $E_{\alpha,\beta}(-z)$ is completely monotonic if and only if $0 < \alpha \leq \min(\beta, 1)$. Then the Bernstein theorem (see, e.g. [38, Theorem 12a]) implies that the function $f(x)$ is nonnegative. □

Lemma 4.6: *The nonnegative statements in Theorem 3.1 hold true.*

Proof: We first prove the case (a). In this case, $\beta \in (0, 1]$. When $\beta = 1$, Z and Y coincide and they are alpha stable densities. Hence, we need only consider the case $\beta \in (0, 1)$. Because $\lim_{t \rightarrow 0} Z_{\alpha,\beta,d}(t, x) = 0$ for all $|x| \neq 0$, and noticing that $I_t^{1-\beta} \partial^{1-\beta} = Id$ (see, e.g. Theorem 3.8 of [11]), we see that

$$Z_{\alpha,\beta,d}(t, x) = I_t^{1-\beta} \partial^{1-\beta} Z_{\alpha,\beta,d}(t, x) = I_t^{1-\beta} Y_{\alpha,\beta,d}(t, x).$$

Hence, it suffices to show the nonnegativity of $Y_{\alpha,\beta,d}(t, x)$. Notice that by Property 1.5,

$$\begin{aligned} J &:= \int_0^\infty \frac{ds}{s} H_{1,2}^{1,1} \left(\frac{|x|^\alpha}{2^{\alpha-1} \nu} s^\beta \mid \begin{matrix} (1,1) \\ (d/2,\alpha/2), (1,\alpha/2) \end{matrix} \right) H_{1,1}^{1,0} \left((ts)^{-\beta} \mid \begin{matrix} (\beta,\beta) \\ (1,1) \end{matrix} \right) \\ &= \beta^{-2} \int_0^\infty \frac{ds}{s} H_{1,2}^{1,1} \left(\frac{|x|^{\alpha/\beta}}{2^{(\alpha-1)/\beta} \nu^{1/\beta}} s \mid \begin{matrix} (1,1/\beta) \\ (d/2,\alpha/2\beta), (1,\alpha/2\beta) \end{matrix} \right) H_{1,1}^{1,0} \left(\frac{1}{ts} \mid \begin{matrix} (\beta,1) \\ (1,1/\beta) \end{matrix} \right). \end{aligned}$$

Now we check conditions in Theorem 1.8. Condition (1) of Theorem 1.8 is satisfied because $a_1^* = 1/\beta > 0$ and $a_2^* = (1 - \beta)/\beta > 0$. Condition (A16) of Theorem 1.8 holds because

$$A_1 = 0, \quad A_2 = \beta, \quad B_1 = d\beta/\alpha, \quad B_2 = \infty.$$

Hence, Theorem 1.8 implies that

$$J = \beta^{-2} H_{2,3}^{2,1} \left(\frac{|x|^{\alpha/\beta}}{t^{2(\alpha-1)/\beta} v^{1/\beta}} \left| \begin{matrix} (1,1/\beta), (\beta,1) \\ (d/2, \alpha/2\beta), (1,1/\beta), (1, \alpha/2\beta) \end{matrix} \right. \right).$$

Then by Property 1.5, we see that

$$Y(t, x) = \beta \pi^{-d/2} t^{\beta-1} |x|^{-d} \int_0^\infty ds s^{-1} H_{1,2}^{1,1} \left(\frac{|x|^\alpha}{2^{\alpha-1} v} s^\beta \left| \begin{matrix} (1,1) \\ (d/2, \alpha/2), (1, \alpha/2) \end{matrix} \right. \right) H_{1,1}^{1,0} \left((ts)^{-\beta} \left| \begin{matrix} (\beta, \beta) \\ (1,1) \end{matrix} \right. \right).$$

By Lemma 4.5, the second H-function in the above equation is nonnegative. On the other hand, Theorem 3.3 tells us that the first H-function is nonnegative. Thus, $Y(t, x)$ is nonnegative.

As for the case (b), it is known from [31] that $Y_{2,\beta,d}$ is nonnegative for $d \leq 3$. By the same argument as in the proof of (a), $Z_{2,\beta,d}$ is also nonnegative.

Finally, for the case (c), it is proved in [25] that $Z_{\alpha,\beta,1}^*(t, x)$ is nonnegative. By the same reason as in the proof of (a), $Y_{\alpha,\beta,1}$ and $Z_{\alpha,\beta,1}$ are fractional integrals of $Z_{\alpha,\beta,1}^*$ of orders $1 - \beta$ and 1 , respectively. Therefore, both $Y_{\alpha,\beta,1}$ and $Z_{\alpha,\beta,1}$ are nonnegative as well. The proof of Lemma 4.6 is now complete. □

Proof of Theorem 3.3: The Theorem 3.1 follows from the above lemmas. □

4.2. Proof of Theorem 3.3

Proof of Theorem 3.3: The characteristic function (3.14) of X is proved in [37, (7.5.3) on p.211]. For the density $\rho_{\alpha,d}$, we need to compute the inverse Fourier transform. From [37, (7.5.5)] this inverse transform is

$$\rho_{\alpha,d}(r) = (2\pi)^{-d/2} r^{1-d/2} \int_0^\infty e^{-t^\alpha} J_{(d-2)/2}(rt) t^{d/2} dt.$$

By (A21) and (A22), we have that

$$t^{(d+2)/2} J_{(d-2)/2}(rt) = (2/r)^{(d+2)/2} H_{0,2}^{1,0} \left(\frac{r^2 t^2}{4} \left| \overline{(d/2, 1), (1, 1)} \right. \right)$$

and

$$e^{-t^\alpha} = \frac{1}{\alpha} H_{0,1}^{1,0} \left(t \left| \overline{(0, 1/\alpha)} \right. \right).$$

Hence,

$$\rho_{\alpha,d}(r) = \pi^{-d/2} r^{-d} \int_0^\infty t^{-1} H_{0,2}^{1,0} \left(\left(\frac{rt}{2} \right)^\alpha \left| \overline{(d/2, \alpha/2), (1, \alpha/2)} \right. \right) H_{0,1}^{1,0} \left(t \left| \overline{(0, 1/\alpha)} \right. \right) dt.$$

Application of Theorem 1.8 to evaluate the above integral yields the theorem. □

5. Proof of Theorem 3.5

Proof of Theorem 3.5: Recall that $J_0(t, x)$ defined by (1.4) is the solution to the homogeneous equation.

Using an iteration procedure as in [19], we have

$$f_n(s_1, x_1, \dots, s_n, x_n, t, x) = g_n(s_1, x_1, \dots, s_n, x_n, t, x)J_0(s_{\sigma(1)}, x_{\sigma(1)})$$

where

$$g_n(s_1, x_1, \dots, s_n, x_n, t, x) = \frac{1}{n!} Y(t - s_{\sigma(n)}, x - x_{\sigma(n)}) \dots Y(s_{\sigma(2)} - s_{\sigma(1)}, x_{\sigma(2)} - x_{\sigma(1)}),$$

and σ denotes a permutation of $\{1, 2, \dots, n\}$ such that $0 < s_{\sigma(1)} < \dots < s_{\sigma(n)} < t$. Fix $t > 0$ and $x \in \mathbb{R}^d$, set $f_n(s, y, t, x) = f_n(s_1, y_1, \dots, s_n, y_n, t, x)$. Then we have that

$$\begin{aligned} & n! \|f_n(\cdot, \cdot, t, x)\|_{\mathcal{H}^{\otimes n}}^2 \\ &= n! \int_{[0,t]^{2n}} ds dr \int_{\mathbb{R}^{2nd}} dy dz f_n(s, y, t, x) f_n(r, z, t, x) \prod_{i=1}^n \Lambda(y_i - z_i) \prod_{i=1}^n \gamma(s_i - r_i). \end{aligned} \tag{5.1}$$

where $dy = dy_1 \dots dy_n$, the differentials dz , ds and dr are defined similarly. Set $\mu(d\xi) := \prod_{i=1}^n \mu(d\xi_i)$. Using the Fourier transform and Cauchy–Schwartz inequality together with (2.8), we obtain that

$$\begin{aligned} & n! \|f_n(\cdot, \cdot, t, x)\|_{\mathcal{H}^{\otimes n}}^2 \\ & \leq \frac{\widehat{C}_t^2 n!}{(2\pi)^{nd}} \int_{[0,t]^{2n}} \int_{\mathbb{R}^{nd}} \mathcal{F}g_n(s, \cdot, t, x)(\xi) \overline{\mathcal{F}g_n(r, \cdot, t, x)(\xi)} \mu(d\xi) \prod_{i=1}^n \gamma(s_i - r_i) ds dr \\ & \leq \frac{\widehat{C}_t^2 n!}{(2\pi)^{nd}} \int_{[0,t]^{2n}} \left(\int_{\mathbb{R}^{nd}} (\mathcal{F}g_n(s, \cdot, t, x)(\xi))^2 \mu(d\xi) \right)^{1/2} \\ & \quad \times \left(\int_{\mathbb{R}^{nd}} (\mathcal{F}g_n(r, \cdot, t, x)(\xi))^2 \mu(d\xi) \right)^{1/2} \prod_{i=1}^n \gamma(s_i - r_i) ds dr, \end{aligned} \tag{5.2}$$

where the constant \widehat{C}_t is defined in (3.16). Thus, thanks to the basic inequality $ab \leq 2^{-1}(a^2 + b^2)$ and the fact that γ is locally integrable, we obtain

$$\begin{aligned} n! \|f_n(\cdot, \cdot, t, x)\|_{\mathcal{H}^{\otimes n}}^2 & \leq \frac{\widehat{C}_t^2 n!}{(2\pi)^{nd}} \int_{[0,t]^{2n}} \int_{\mathbb{R}^{nd}} |\mathcal{F}g_n(s, \cdot, t, x)(\xi)|^2 \mu(d\xi) \prod_{i=1}^n \gamma(s_i - r_i) ds dr \\ & \leq \frac{\widehat{C}_t^2 C_t^n n!}{(2\pi)^{nd}} \int_{[0,t]^n} ds \int_{\mathbb{R}^{nd}} |\mathcal{F}g_n(s, \cdot, t, x)(\xi)|^2 \mu(d\xi), \end{aligned}$$

where the constant C_t is defined in (2.2). Furthermore, from the Fourier transform of $Y(t, \cdot)$ we can check that

$$\begin{aligned}
 & |\mathcal{F}g_n(r, \cdot, t, x)(\xi)|^2 \\
 &= \frac{1}{(n!)^2} \prod_{i=1}^n \left[(s_{\sigma(i+1)} - s_{\sigma(i)})^{\beta-1} E_{\beta, \beta} \left(-2^{-1} \nu (s_{\sigma(i+1)} - s_{\sigma(i)})^\beta |\xi_{\sigma(i)} + \dots + \xi_{\sigma(1)}|^\alpha \right) \right]^2,
 \end{aligned}$$

where we have set $s_{\sigma(n+1)} = t$. As a consequence,

$$\begin{aligned}
 & \int_{\mathbb{R}^{nd}} |\mathcal{F}g_n(s, \cdot, t, x)(\xi)|^2 \mu(d\xi) \\
 & \leq \frac{1}{(n!)^2} \prod_{i=1}^n \sup_{\eta} \left| \int_{\mathbb{R}^d} (Y(s_{\sigma(i+1)} - s_{\sigma(i)}, \cdot) * Y(s_{\sigma(i+1)} - s_{\sigma(i)}, \cdot))(x_{\sigma(i)}) e^{i\eta \cdot x_{\sigma(i)}} \Lambda(x_{\sigma(i)}) dx_{\sigma(i)} \right| \\
 & \leq \frac{1}{(n!)^2} \prod_{i=1}^n \left| \int_{\mathbb{R}^d} (Y(s_{\sigma(i+1)} - s_{\sigma(i)}, \cdot) * Y(s_{\sigma(i+1)} - s_{\sigma(i)}, \cdot))(x_{\sigma(i)}) \Lambda(x_{\sigma(i)}) dx_{\sigma(i)} \right| \\
 & \leq \frac{1}{(n!)^2} \prod_{i=1}^n \int_{\mathbb{R}^d} [(s_{\sigma(i+1)} - s_{\sigma(i)})^{\beta-1} E_{\beta, \beta} \left(-2^{-1} \nu (s_{\sigma(i+1)} - s_{\sigma(i)})^\beta |\xi_{\sigma(i)}|^\alpha \right)]^2 \mu(d\xi_{\sigma(i)}), \quad (5.3)
 \end{aligned}$$

where we have used the fact that $|e^{ix_{\sigma(i)} \cdot \eta}| = 1$ and that Y and Λ are nonnegative to get rid of the supremum in η . Therefore, using Fourier transform again we have

$$\begin{aligned}
 n! \|f_n(\cdot, \cdot, t, x)\|_{\mathcal{H}^{\otimes n}}^2 & \leq \frac{\widehat{C}_t^2 C_t^n}{(2\pi)^{nd}} \int_{\mathbb{R}^{nd}} \mu(d\xi) \int_{T_n(t)} ds \\
 & \quad \times \prod_{i=1}^n (s_{i+1} - s_i)^{2\beta-2} E_{\beta, \beta}^2 \left(-2^{-1} \nu (s_{i+1} - s_i)^\beta |\xi_i|^\alpha \right), \quad (5.4)
 \end{aligned}$$

where $T_n(t)$ denotes the simplex

$$T_n(t) := \{s = (s_1, \dots, s_n) : 0 < s_1 < \dots < s_n < t\}. \quad (5.5)$$

By the change of variables $s_{i+1} - s_i = w_i$ for $1 \leq i \leq n - 1$ and $t - s_n = w_n$, we see that

$$n! \|f_n(\cdot, \cdot, t, x)\|_{\mathcal{H}^{\otimes n}}^2 \leq \frac{\widehat{C}_t^2 C_t^n}{(2\pi)^{nd}} \int_{\mathbb{R}^{nd}} \int_{S_{t,n}} \prod_{i=1}^n w_i^{2\beta-2} E_{\beta, \beta}^2 \left(-2^{-1} \nu w_i^\beta |\xi_i|^\alpha \right) dw_i \mu(d\xi_i),$$

where

$$S_{t,n} = \{(w_1, \dots, w_n) \in [0, \infty)^n : w_1 + \dots + w_n \leq t\}.$$

We take $N \geq 1$ which will be chosen later, and let

$$C_N = \int_{|\xi| \geq N} \frac{\mu(d\xi)}{|\xi|^{2\alpha-\alpha/\beta}} \quad \text{and} \quad D_N = \mu\{\xi \in \mathbb{R}^d : |\xi| \leq N\}. \quad (5.6)$$

Let I be a subset of $\{1, 2, \dots, n\}$ and $I^c = \{1, 2, \dots, n\} \setminus I$. Then we have

$$\begin{aligned} & \int_{\mathbb{R}^{nd}} \int_{S_{t,n}} \prod_{i=1}^n w_i^{2\beta-2} E_{\beta,\beta}^2(-2^{-1} \nu w_i^\beta |\xi_i|^\alpha) dw_i \mu(d\xi_i) \\ &= \int_{\mathbb{R}^{nd}} \int_{S_{t,n}} \prod_{i=1}^n w_i^{2\beta-2} E_{\beta,\beta}^2(-2^{-1} \nu w_i^\beta |\xi_i|^\alpha) (\mathbf{1}_{\{|\xi_i| \leq N\}} + \mathbf{1}_{\{|\xi_i| > N\}}) dw_i \mu(d\xi_i) \\ &= \sum_{I \subset \{1, 2, \dots, n\}} \int_{\mathbb{R}^{nd}} dw \int_{S_{t,n}} \mu(d\xi) \prod_{i \in I} E_{\beta,\beta}^2(-2^{-1} \nu w_i^\beta |\xi_i|^\alpha) w_i^{2\alpha-2} \mathbf{1}_{\{|\xi_i| \leq N\}} \\ & \quad \times \prod_{j \in I^c} E_{\beta,\beta}^2(-2^{-1} \nu w_j^\beta |\xi_j|^\alpha) w_j^{2\beta-2} \mathbf{1}_{\{|\xi_j| > N\}}. \end{aligned}$$

where $dw = dw_1 \dots dw_n$. For the indices i in the set I , for some constant $C_\beta \geq 1$ (one may choose $C_\beta = \Gamma(\beta)^{-2}$)

$$E_{\beta,\beta}^2(-2^{-1} \nu w_i^\beta |\xi_i|^\alpha) \leq C_\beta. \tag{5.7}$$

Now using the inclusion $S_{t,n} \subset S_t^I \times S_t^{I^c}$ with

$$S_t^I = \left\{ (w_i, i \in I) : w_i \geq 0, \sum_{i \in I} w_i \leq t \right\} \quad \text{and} \quad S_t^{I^c} = \left\{ (w_i, i \in I^c) : w_i \geq 0, \sum_{i \in I^c} w_i \leq t \right\},$$

we obtain that

$$\begin{aligned} & \int_{\mathbb{R}^{nd}} \int_{S_{t,n}} \prod_{i=1}^n w_i^{2\beta-2} E_{\beta,\beta}^2(-2^{-1} \nu w_i^\beta |\xi_i|^\alpha) dw_i \mu(d\xi_i) \\ & \leq C_\beta^{|I|} \sum_{I \subset \{1, 2, \dots, n\}} \int_{\mathbb{R}^{nd}} \mu(d\xi) \int_{S_t^I \times S_t^{I^c}} dw \\ & \quad \times \prod_{i \in I} w_i^{2\beta-2} \mathbf{1}_{\{|\xi_i| \leq N\}} \prod_{j \in I^c} w_j^{2\beta-2} \mathbf{1}_{\{|\xi_j| > N\}} E_{\beta,\beta}^2(-2^{-1} \nu w_j^\beta |\xi_j|^\alpha). \end{aligned}$$

Furthermore, one can bound the integral over $S_t^{I^c}$ in the following way

$$\int_{S_t^{I^c}} \prod_{j \in I^c} w_j^{2\beta-2} E_{\beta,\beta}^2(-2^{-1} \nu w_j^\beta |\xi_j|^\alpha) dw_j \leq \int_{\mathbb{R}_+^{|I^c|}} \prod_{j \in I^c} w_j^{2\beta-2} E_{\beta,\beta}^2(-2^{-1} \nu w_j^\beta |\xi_j|^\alpha) dw_j.$$

Then make the change of variables $w_j^\beta |\xi_j|^\alpha \rightarrow v_j$ to obtain

$$\begin{aligned} & \int_{[0, \infty)^{|I^c|}} \prod_{j \in I^c} w_j^{2\beta-2} E_{\beta,\beta}^2(-2^{-1} \nu w_j^\beta |\xi_j|^\alpha) dw_j \\ & \leq \prod_{j \in I^c} \frac{1}{|\xi_j|^{2\alpha-\alpha/\beta}} \int_0^\infty \frac{1}{\beta} v_j^{1-1/\beta} E_{\beta,\beta}^2(-2^{-1} \nu v_j) dv_j \end{aligned}$$

$$\leq C_{v,\beta}^{|I^c|} \prod_{j \in I^c} \frac{1}{|\xi_j|^{2\alpha-\alpha/\beta}},$$

where

$$C_{v,\beta} = \int_0^\infty \frac{1}{\beta} v^{1-1/\beta} E_{\beta,\beta}^2(-2^{-1}v) dv.$$

Note that the integrability of the above quantity at zero and at infinity implies that $\beta > 1/2$ and $\beta > 0$, respectively. Thus we have the following bound.

$$\begin{aligned} & \int_{\mathbb{R}^{nd}} \int_{S_{t,n}} \prod_{i=1}^n w_i^{2\beta-2} E_{\beta,\beta}^2(-2^{-1}v w_i^\beta |\xi_i|^\alpha) dw_i \mu(d\xi_i) \\ & \leq \sum_{I \subset \{1,2,\dots,n\}} C_\beta^{|I|} \int_{S_t^I} \prod_{i \in I} w_i^{2\beta-2} dw_i \cdot \left(\mu\{\xi \in \mathbb{R}^d : |\xi| \leq N\}\right)^{|I|} C_{v,\beta}^{|I^c|} \int_{|\xi_j| > N, \forall j \in I^c} \prod_{j \in I^c} \frac{\mu(d\xi_j)}{|\xi_j|^{2\alpha-\alpha/\beta}} \\ & \leq \sum_{I \subset \{1,2,\dots,n\}} \frac{C_\beta^{|I|} t^{(2\beta-1)|I|} C_{v,\beta}^{|I^c|}}{\Gamma((2\beta-1)|I|+1)} D_N^{|I|} C_N^{n-|I|} \\ & \leq C_*^n \sum_{k=0}^n \binom{n}{k} \frac{t^{(2\beta-1)k}}{\Gamma((2\beta-1)k+1)} D_N^k C_N^{n-k}. \end{aligned}$$

where $C_* = \max(C_\beta, C_{v,\beta})$, and C_N and D_N are defined in (5.6). Observing the trivial inequality $\binom{n}{k} \leq 2^n$, we have

$$\begin{aligned} \sum_{n=0}^\infty n! \|f_n(\cdot, \cdot, t, x)\|_{\mathcal{H}^{\otimes n}}^2 & \leq \frac{\widehat{C}_t^2}{(2\pi)^{nd}} \sum_{k=0}^\infty \sum_{n=k}^\infty \binom{n}{k} (C_* C_t)^n \frac{t^{(2\beta-1)k}}{\Gamma((2\beta-1)k+1)} D_N^k C_N^{n-k} \\ & \leq \frac{\widehat{C}_t^2}{(2\pi)^{nd}} \sum_{k=0}^\infty \sum_{n=k}^\infty \frac{t^{(2\beta-1)k}}{\Gamma((2\beta-1)k+1)} D_N^k C_N^{-k} (2C_* C_t C_N)^n. \end{aligned}$$

Choosing N sufficiently large so that $2C_* C_t C_N < 1$ yields

$$\sum_{n=0}^\infty n! \|f_n(\cdot, \cdot, t, x)\|_{\mathcal{H}^{\otimes n}}^2 \leq \frac{\widehat{C}_t^2}{(2\pi)^{nd}} \sum_{k=0}^\infty \frac{t^{(2\beta-1)k}}{\Gamma((2\beta-1)k+1)} D_N^k C_N^{-k} \frac{(2C_* C_t C_N)^k}{1 - 2C_* C_t C_N} < \infty.$$

This proves (2.7), and thus the existence and uniqueness of the solution. □

6. Proof of Theorem 3.11

Lemma 6.1: *Suppose that the initial conditions $u_k(x) \equiv u_k$ are constant. Then under the three cases of (1.6), we have that*

$$J_0(t, x) = \begin{cases} u_0 & \text{if } \beta \in (0, 1], \\ u_0 + t^{\beta-1} u_1 & \text{if } \beta \in (1, 2). \end{cases} \tag{6.1}$$

Proof: By Theorem 3.1, we know that under the first two cases of (1.6), the fundamental solutions are nonnegative and hence,

$$J_0(t, x) = \sum_{k=0}^{\lceil \beta \rceil - 1} u_{\lceil \beta \rceil - 1 - k} \int_{\mathbb{R}^d} \partial^k Z(t, x - y) dy = \sum_{k=0}^{\lceil \beta \rceil - 1} u_{\lceil \beta \rceil - 1 - k} \mathcal{F} \left[\partial^k Z(t, \cdot) \right] (0),$$

which is equal to the right hand side of (6.1). As for the last case in (1.6), because Z is still nonnegative, the contribution by u_0 can be computed in the same way. However, we do not know whether Z^* is nonnegative, and thus we cannot use the Fourier transform arguments to compute the contribution by u_1 . Instead, we compute it directly:

$$\int_{\mathbb{R}^d} Z_{2,\beta,d}^*(t, x) dx = S_{d-1} \pi^{-d/2} \int_0^\infty x^{-1} H_{1,2}^{2,0} \left(\frac{x^\alpha}{2\nu t^\beta} \middle| \begin{matrix} (1,\beta) \\ (d/2,1), (1,1) \end{matrix} \right) dx,$$

where

$$S_{d-1} = \frac{2\pi^{d/2}}{\Gamma(d/2)}. \tag{6.2}$$

Then by Theorem 1.9, we have the following Laplace transform:

$$g(z) := \int_0^\infty e^{-zx} x^{-1} H_{1,2}^{2,0} \left(\frac{x^\alpha}{2\nu t^\beta} \middle| \begin{matrix} (1,\beta) \\ (d/2,1), (1,1) \end{matrix} \right) dx = H_{2,2}^{1,2} \left(2\nu t^\beta z^2 \middle| \begin{matrix} (1-d/2,1), (0,1) \\ (0,\alpha), (0,\beta) \end{matrix} \right).$$

Then by Theorem 1.7,

$$g(0) = h_{10}^* = \frac{\Gamma(d/2)}{2}.$$

Putting these identities together, we have that

$$\int_{\mathbb{R}^d} Z_{2,\beta,d}^*(t, x) dx = 1.$$

This completes the proof of Lemma 6.1. □

Proof of Theorem 3.11: Since $\Lambda(x) = |x|^{-\kappa}$, we have $\mu(d\xi) = C_\kappa |\xi|^{\kappa-d}$, for some coefficient C_κ ; see, e.g. [35]. We begin with the upper bound. By the hypercontractivity property of the n -th chaos, i.e.

$$\|I_n(f_n(\cdot, \cdot, t, x))\|_{L^p(\Omega)} \leq (p-1)^{\frac{n}{2}} \|I_n(f_n(\cdot, \cdot, t, x))\|_{L^2(\Omega)}. \tag{6.3}$$

On the other hand, from the proof of Theorem 3.5 (see (5.4)) it follows

$$\begin{aligned} \|I_n(f_n(\cdot, \cdot, t, x))\|_{L^2(\Omega)}^2 &= n! \|f_n(\cdot, \cdot, t, x)\|_{\mathcal{H}^{\otimes n}}^2 \\ &\leq \frac{\widehat{C}_t^2 C_\kappa^n C_t^n}{(2\pi)^{nd}} \int_{T_n(t)} \int_{\mathbb{R}^{nd}} \prod_{i=1}^n (s_{i+1} - s_i)^{2\beta-2} E_{\beta,\beta}^2(-2^{-1}\nu(s_{i+1} - s_i)^\beta |\xi_i|^\alpha) |\xi_i|^{\kappa-d} d\xi_i ds_i \\ &= \frac{\widehat{C}_t^2 C_\kappa^n C_t^n (2/\nu)^{\kappa n/\alpha}}{(2\pi)^{nd}} \int_{T_n(t)} \int_{\mathbb{R}^{nd}} \prod_{i=1}^n (s_{i+1} - s_i)^{2\beta-2-\frac{\beta\kappa}{\alpha}} E_{\beta,\beta}^2(-|\eta_i|^\alpha) |\eta_i|^{\kappa-d} d\eta_i ds_i \end{aligned}$$

$$= \frac{\widehat{C}_t^2 C_\kappa^n C_t^n (2/\nu)^{\kappa n/\alpha} \widetilde{C}^n}{(2\pi)^{nd}} \int_{T_n(t)} \prod_{i=1}^n (s_{i+1} - s_i)^{2\beta - 2 - \frac{\beta\kappa}{\alpha}} ds_i,$$

where \widehat{C}_t is defined in (3.16),

$$\widetilde{C} := \int_{\mathbb{R}^d} E_{\beta,\beta}^2(-|\eta|^\alpha) |\eta|^{\kappa-d} d\eta = S_{d-1} \int_0^\infty E_{\beta,\beta}^2(-t^\alpha) t^{\kappa-1} dt,$$

and S_{d-1} is defined in (6.2). According to the property of the Mittag–Leffler function at zero and infinity, if $0 < \kappa < 2\alpha$, then the above constant \widetilde{C} is finite. Then, under the condition that $\kappa < \alpha(2 - 1/\beta)$ (this condition implies $0 < \kappa < 2\alpha$), the integration over ds can be evaluated explicitly; see [19, Lemma 4.5]. Hence,

$$\|I_n(f_n(\cdot, \cdot, t, x))\|_{L^2(\Omega)}^2 \leq \frac{1}{(2\pi)^{nd}} (C_\kappa C_* C_t \widetilde{C})^n \frac{t^{(2\beta-1-\frac{\beta\kappa}{\alpha})n} (2/\nu)^{\kappa n/\alpha}}{\Gamma((2\beta-1-\frac{\beta\kappa}{\alpha})n+1)},$$

where $C_* := \Gamma(2\beta - 1 - \beta\kappa/\alpha)$. Denote

$$\Theta_t := \frac{1}{(2\pi)^d} C_\kappa C_* C_t \widetilde{C} (2/\nu)^{\kappa/\alpha}.$$

Thus we obtain

$$\|I_n(f_n(\cdot, \cdot, t, x))\|_{L^2(\Omega)} \leq \widehat{C}_t \frac{\Theta_t^{n/2} t^{(\beta-\frac{1}{2}-\frac{\beta\kappa}{2\alpha})n}}{\Gamma((2\beta-1-\frac{\beta\kappa}{\alpha})n+\frac{1}{2})}. \tag{6.4}$$

This bound together with the hypercontractivity implies that

$$\|I_n(f_n(\cdot, \cdot, t, x))\|_{L^p(\Omega)} \leq \widehat{C}_t \frac{\Theta_t^{n/2} t^{(\beta-\frac{1}{2}-\frac{\beta\kappa}{2\alpha})n} (p-1)^{\frac{n}{2}}}{\Gamma((2\beta-1-\frac{\beta\kappa}{\alpha})n+\frac{1}{2})}. \tag{6.5}$$

Therefore,

$$\|u(t, x)\|_{L^p(\Omega)} \leq \sum_{n=0}^\infty \|I_n(f_n(\cdot, \cdot, t, x))\|_{L^p(\Omega)} \leq \widehat{C}_t \sum_{n=0}^\infty \frac{\Theta_t^{n/2} t^{\theta n} p^{\frac{n}{2}}}{\Gamma(2\theta n + 1)^{\frac{1}{2}}}.$$

where

$$\theta := \beta - 1/2 - \beta\kappa/(2\alpha). \tag{6.6}$$

Then by the fact that $\Gamma(1 + 2x) \geq \Gamma(1 + x)^2$ for $x > -1$,

$$\begin{aligned} \|u(t, x)\|_{L^p(\Omega)} &\leq \widehat{C}_t \sum_{n=0}^\infty \frac{\Theta_t^{n/2} t^{\theta n} p^{\frac{n}{2}}}{\Gamma(\theta n + 1)} = \widehat{C}_t E_\theta \left(\Theta_t^{1/2} t^\theta p^{1/2} \right) \\ &\leq C \widehat{C}_t \exp \left(t (C_\kappa C_t \widetilde{C} C_* (2/\nu)^{\kappa/\alpha} (2\pi)^{-d})^{\frac{\alpha}{2\alpha\beta-\alpha-\beta\kappa}} p^{\frac{\alpha}{2\alpha\beta-\alpha-\beta\kappa}} \right), \end{aligned}$$

for some positive constant $C = C(\alpha, \beta, \kappa)$, where in the last step, we have used the asymptotic property of the Mittag–Leffler function (see, e.g. [30, Theorem 1.3]).

Now we consider the special case when γ is the Dirac delta function. By Lemma 6.1 and the assumptions on the initial conditions we have

$$J_0(t, x) = u_0 + t^{\beta-1} u_1 1_{\{\beta>1\}} = u_0.$$

From the proof of Theorem 3.5 (see (5.2) and (5.4)), we see that

$$\begin{aligned} \|I_n(f_n(\cdot, \cdot, t, x))\|_{L^2(\Omega)}^2 &= \frac{1}{n!} \frac{u_0^2 C_\kappa^n}{(2\pi)^{nd}} \int_{[0,t]^n} ds \int_{\mathbb{R}^{nd}} d\xi \prod_{i=1}^n (s_{\sigma(i+1)} - s_{\sigma(i)})^{2\beta-2} \\ &\quad \times E_{\beta,\beta}^2 (-2^{-1} \nu (s_{\sigma(i+1)} - s_{\sigma(i)})^\beta |\xi_{\sigma(i)} + \dots + \xi_{\sigma(1)}|^\alpha) |\xi_i|^{\kappa-d} \\ &= \frac{u_0^2 C_\kappa^n}{(2\pi)^{nd}} \int_{T_n(t)} ds \int_{\mathbb{R}^{nd}} d\xi \prod_{i=1}^n (s_{i+1} - s_i)^{2\beta-2} \\ &\quad \times E_{\beta,\beta}^2 (-2^{-1} \nu (s_{i+1} - s_i)^\beta |\xi_i + \dots + \xi_1|^\alpha) |\xi_i|^{\kappa-d}. \end{aligned}$$

Then by the change of variable $\xi_i + \dots + \xi_1 = \eta_i$ and replacing \mathbb{R}^{nd} by \mathbb{R}_+^{nd} , we obtain that

$$\begin{aligned} \|I_n(f_n(\cdot, \cdot, t, x))\|_{L^2(\Omega)}^2 &= \frac{u_0^2 C_\kappa^n}{(2\pi)^{nd}} \int_{T_n(t)} \int_{\mathbb{R}^{nd}} \prod_{i=1}^n (s_{i+1} - s_i)^{2\beta-2} \\ &\quad \times E_{\beta,\beta}^2 (-2^{-1} \nu (s_{i+1} - s_i)^\beta |\eta_i|^\alpha) |\eta_i - \eta_{i-1}|^{\kappa-d} d\xi_i ds_i \\ &\geq \frac{u_0^2 C_\kappa^n}{(2\pi)^{nd}} \int_{T_n(t)} \int_{\mathbb{R}_+^{nd}} \prod_{i=1}^n (s_{i+1} - s_i)^{2\beta-2} \\ &\quad \times E_{\beta,\beta}^2 (-2^{-1} \nu (s_{i+1} - s_i)^\beta |\eta_i|^\alpha) |\eta_i - \eta_{i-1}|^{\kappa-d} d\xi_i ds_i \\ &\geq \frac{u_0^2 C_\kappa^n}{(2\pi)^{nd}} \int_{T_n(t)} \int_{\mathbb{R}_+^{nd}} \prod_{i=1}^n (s_{i+1} - s_i)^{2\beta-2} \\ &\quad \times E_{\beta,\beta}^2 (-2^{-1} \nu (s_{i+1} - s_i)^\beta |\eta_i|^\alpha) |\eta_i|^{\kappa-d} d\xi_i ds_i, \end{aligned}$$

where $\eta_0 = 0$. Then with another change of variable $(\nu/2)^{1/\alpha} (s_{i+1} - s_i)^{\beta/\alpha} \eta_i \rightarrow \eta_i$, and by the same reasoning as before, we obtain that

$$\begin{aligned} \|I_n(f_n(\cdot, \cdot, t, x))\|_{L^2(\Omega)}^2 &\geq \frac{u_0^2 C_\kappa^n}{(2\pi)^{nd}} \int_{T_n(t)} \int_{\mathbb{R}_+^{nd}} \prod_{i=1}^n (s_{i+1} - s_i)^{2\beta-2-\frac{\beta\kappa}{\alpha}} E_{\beta,\beta}^2 (-|\eta_i|^\alpha) |\eta_i|^{\kappa-d} d\xi_i ds_i \\ &= \frac{u_0^2 C_\kappa^n}{(2\pi)^{nd}} \left(\frac{\tilde{C}}{2^d}\right)^n (2/\nu)^{\frac{\kappa n}{\alpha}} \int_{T_n(t)} \prod_{i=1}^n (s_{i+1} - s_i)^{2\beta-2-\frac{\beta\kappa}{\alpha}} ds_i \\ &= \frac{t^{n(2\beta-1-\frac{\beta\kappa}{\alpha})} (2/\nu)^{\kappa n/\alpha} u_0^2 C_\kappa^n \tilde{C}^n (4\pi)^{-nd} C_n^*}{\Gamma(n(2\beta-1-\frac{\beta\kappa}{\alpha})+1)}. \end{aligned}$$

Therefore, by the asymptotic property of the Mittag–Leffler function,

$$\begin{aligned} \mathbb{E} [u(t, x)^2] &\geq \sum_{n=0}^{\infty} \frac{u_0^2 (C_\kappa \tilde{C}(4\pi)^{-d} C_*)^n t^{n(2\beta-1-\frac{\beta\kappa}{\alpha})} (2/\nu)^{\frac{\kappa n}{\alpha}}}{\Gamma(n(2\beta-1-\frac{\beta\kappa}{\alpha})+1)} \\ &\geq c u_0^2 \exp\left((C_\kappa \tilde{C}(4\pi)^{-d} C_*)^{\kappa/\alpha} (2/\nu)^{\frac{1}{2\beta-1-\beta\kappa/\alpha}} t\right), \end{aligned}$$

for some positive constant $c = c(\alpha, \beta, \kappa)$. This completes the proof of Theorem 3.11. \square

7. Proof of Theorem 3.14

In this section, $C = C_{\alpha, \beta, \dots}$ denotes a positive constant, possibly dependent on $\alpha, \beta, d, \nu, \dots$

Lemma 7.1: Assume that $\beta \in (0, 2)$, $\alpha > 0$ and $d \in \mathbb{N}$. Then there is a nonnegative constant $C_{\alpha, \beta, d}$ such that for all $0 < \zeta < \min(d/\alpha, 2)$,

$$\left| H_{2,3}^{2,1} \left(z \mid \begin{matrix} (1,1), (\beta, \beta) \\ (d/2, \alpha/2), (1,1), (1, \alpha/2) \end{matrix} \right) \right| \leq C_{\alpha, \beta, d} \frac{z^\zeta}{z^{\zeta+1} + 1}, \quad \text{for all } z \geq 0.$$

Proof: We first note that condition (A6) is satisfied. Because $a^* = 2 - \beta > 0$, we can apply Theorem 1.6 to obtain that

$$H_{2,3}^{2,1} \left(z \mid \begin{matrix} (1,1), (\beta, \beta) \\ (d/2, \alpha/2), (1,1), (1, \alpha/2) \end{matrix} \right) = O(1/z); \quad z \rightarrow \infty.$$

As for small z , note that the poles of $\Gamma(1 + s)$ are

$$A := \{-(1 + k) : k = 0, 1, 2, \dots\};$$

and those of $\Gamma(d/2 + \alpha s/2)$ are

$$B := \left\{ -\frac{2l + d}{\alpha} : l = 0, 1, 2, \dots \right\}.$$

To find the leading term when $z \rightarrow 0$, we need to find the first nonvanishing residue of $\mathcal{H}_{2,3}^{2,1}(s)z^{-s}$ at poles $A \cup B$, where

$$\mathcal{H}_{2,3}^{2,1}(s) = \frac{\Gamma(d/2 + \alpha s/2)\Gamma(1 + s)\Gamma(-s)}{\Gamma(\beta + \beta s)\Gamma(-\alpha s/2)}. \tag{7.1}$$

Case I When $d \neq \alpha$ and $d \neq 2\alpha$, then the leading pole ($l = 0$) in B does not coincide with the first two poles ($k = 0, 1$) of A . Hence, the asymptotic expansion in Theorem 1.7 (1) implies that

$$H_{2,3}^{2,1} \left(z \mid \begin{matrix} (1,1), (\beta, \beta) \\ (d/2, \alpha/2), (1,1), (1, \alpha/2) \end{matrix} \right) = h_{10}^* z^{d/\alpha} + h_{20}^* z + h_{11}^* z^2 + O(z^2) + O(z^{d/\alpha}); \quad z \rightarrow 0.$$

Here h_{ij}^* are defined in (A12). Notice that $h_{20}^* = 0$ due to the presence of the parameter (β, β) . Hence,

$$H_{2,3}^{2,1} \left(z \mid \begin{matrix} (1,1), (\beta, \beta) \\ (d/2, \alpha/2), (1,1), (1, \alpha/2) \end{matrix} \right) = O(z^2) + O(z^{d/\alpha}); \quad z \rightarrow 0.$$

Case II Now we consider the case when $d = \alpha$. The first pole in $A \cup B$ is $s = -1$, which is of order 2. Now we compute the mentioned residue:

$$\begin{aligned} \operatorname{Res}_{s=-1} \left[\mathcal{H}_{2,3}^{2,1}(s)z^s \right] &= \lim_{s \rightarrow -1} \left[(s+1)^2 \mathcal{H}_{2,3}^{2,1}(s)z^{-s} \right]' \\ &= \lim_{s \rightarrow -1} \left[(s+1)^2 \mathcal{H}_1^*(s) \mathcal{H}_2^*(s)z^{-s} \right]' \\ &= \lim_{s \rightarrow -1} z^{-s} \left[\mathcal{H}_1^*(s)' \mathcal{H}_2^*(s) + \mathcal{H}_1^*(s) \mathcal{H}_2^*(s)' - \mathcal{H}_1^*(s) \mathcal{H}_2^*(s) \log z \right], \end{aligned}$$

where $\mathcal{H}_{2,3}^{2,1}(s)$ is defined in (7.1) and

$$\mathcal{H}_1^*(s) = (s+1)^2 \Gamma((1+s)d/2) \Gamma(1+s) \quad \text{and} \quad \mathcal{H}_2^*(s) = \frac{\Gamma(-s)}{\Gamma(\beta + \beta s) \Gamma(-ds/2)}.$$

Now simple calculations show that

$$\begin{aligned} \mathcal{H}_1^*(-1) &= \lim_{s \rightarrow -1} \mathcal{H}_1^*(s) = \frac{2}{d} = \lim_{s \rightarrow -1} \frac{(1+s)^2}{((1+s)d/2)(1+s)} = \frac{2}{d}, \\ \mathcal{H}_2^*(-1) &= \lim_{s \rightarrow -1} \mathcal{H}_2^*(s) = 0, \\ \frac{d}{ds} \mathcal{H}_2^*(s) \Big|_{s=-1} &= \lim_{s \rightarrow -1} \frac{\Gamma(-s)}{\Gamma(-ds/2)} \left(\frac{1}{\Gamma(\beta(1+s))} \right)' \\ &= \frac{\Gamma(1)}{\Gamma(d/2)} \lim_{s \rightarrow -1} - \frac{\psi(\beta(1+s))}{\Gamma(\beta(1+s))} \\ &= \frac{\beta}{\Gamma(d/2)}, \end{aligned}$$

where $\psi(z)$ is the digamma function and the last limit is due to (5.7.6) and (5.7.1) of [29]. Thus,

$$\begin{aligned} \mathcal{H}_1^*(-1) \mathcal{H}_2^*(-1) &= \mathcal{H}_1^*(-1)' \mathcal{H}_2^*(-1) = 0 \quad \text{and} \\ \mathcal{H}_1^*(-1) \mathcal{H}_2^*(-1)' &= \frac{2\beta}{d\Gamma(d/2)} = \frac{\beta}{\Gamma(1+d/2)}. \end{aligned}$$

Hence,

$$\operatorname{Res}_{s=-1} \left[\mathcal{H}_{2,3}^{2,1}(s)z^s \right] = \frac{\beta z}{\Gamma(1+d/2)}.$$

Therefore, by the definition of the Fox H-function,

$$H_{2,3}^{2,1} \left(z \mid \begin{matrix} (1,1), (\beta,\beta) \\ (d/2,d/2), (1,1), (1,d/2) \end{matrix} \right) = O(z); \quad z \rightarrow 0.$$

Case III As for the case $d = 2\alpha$, the first pole in $A \cup B$ is $s = -1$, which is a simple pole. As calculated before, the residue at this pole is vanishing, $h_{20}^*z \equiv 0$. Hence, we need to consider the next pole at $s = -2$, which is a pole of order 2. Use the asymptotic expansion (A11) to obtain that

$$H_{2,3}^{2,1} \left(z \mid \begin{matrix} (1,1), (\beta,\beta) \\ (d/2,\alpha/2), (1,1), (1,\alpha/2) \end{matrix} \right) = O(z^2 \log z); \quad z \rightarrow 0.$$

Finally, because $a^* > 0$, by Theorem 1.2, our H-function is a continuous function for $z > 0$. With this, we complete the proof of Lemma 7.1. \square

Lemma 7.2: For all $\alpha \in (0, 2]$, $d \in \mathbb{N}$ and $\kappa < \min\{2\alpha, d\}$, one can find $\zeta < \min(d/\alpha, 2)$ and a nonnegative constant C (independent of a) such that

$$\int_{\mathbb{R}^d} |x - a|^{-\kappa} \Theta(x) dx \leq C < \infty \quad \text{for all } a \in \mathbb{R}^d,$$

where

$$\Theta(x) = \frac{1}{|x|^{\alpha+d} + |x|^{d-\zeta\alpha}}.$$

Proof: We divide the integral domain into $\{|x| \leq 1\}$ and $\{|x| > 1\}$. Over the domain $\{|x| \leq 1\}$, we have

$$\begin{aligned} \int_{|x| \leq 1} |x - a|^{-\kappa} \Theta(x) dx &\leq \int_{|x| \leq 1} |x - a|^{-\kappa} \frac{1}{|x|^{d-\zeta\alpha}} dx \\ &= \int_{|x| \leq 1, |x| \leq |x-a|} |x - a|^{-\kappa} \frac{1}{|x|^{d-\zeta\alpha}} dx + \int_{|x-a| < |x| \leq 1} |x - a|^{-\kappa} \frac{1}{|x|^{d-\zeta\alpha}} dx \\ &\leq \int_{|x| \leq 1, |x| \leq |x-a|} |x|^{-\kappa} \frac{1}{|x|^{d-\zeta\alpha}} dx + \int_{|x-a| < |x| \leq 1} |x - a|^{-\kappa} \frac{1}{|x - a|^{d-\zeta\alpha}} dx \\ &\leq 2 \int_{|z| \leq 1} \frac{1}{|z|^{\kappa+d-\zeta\alpha}} dz \leq C. \end{aligned}$$

The last inequality is valid since we can choose ζ sufficiently close to $\min(d/\alpha, 2)$ so that $\kappa + d - \zeta\alpha < d$. On the other hand, over the domain $\{|x| > 1\}$, we have

$$\begin{aligned} \int_{|x| > 1} |x - a|^{-\kappa} \Theta(x) dx &\leq \int_{|x| > 1} |x - a|^{-\kappa} \frac{1}{|x|^{\alpha+d}} dx \\ &\leq \int_{|x-a| \geq |x| > 1} |x - a|^{-\kappa} \frac{1}{|x|^{\alpha+d}} dx + \int_{|x| > |x-a| > 1} |x - a|^{-\kappa} \frac{1}{|x|^{\alpha+d}} dx \\ &\quad + \int_{|x| > 1 \geq |x-a|} |x - a|^{-\kappa} \frac{1}{|x|^{\alpha+d}} dx \\ &\leq 2 \int_{|z| > 1} \frac{1}{|z|^{\alpha+d}} dz + \int_{|z| \leq 1} |z|^{-\kappa} dz \leq C. \end{aligned}$$

Note that the above constant C does not depend on a . \square

Lemma 7.3: Assume $\kappa < \min\{2\alpha, d\}$. Then for all $s, r > 0$ and $x_2, y_2 \in \mathbb{R}^d$, we have that

$$\int_{\mathbb{R}^{2d}} |Y(s, x_1 - x_2) Y(r, y_1 - y_2)| |x_1 - y_1|^{-\kappa} dx_1 dy_1 \leq C_{\alpha, \beta, d, \nu, \kappa} (s r)^\theta,$$

where C does not depend on x_2 and $y_2 \in \mathbb{R}^d$, and

$$\theta := \beta - 1 - \frac{\beta}{2\alpha} \kappa.$$

Proof: We use the notation $\Theta(x)$ in the previous lemma. By Lemma 7.1 and the expression of Y through Fox H-function (3.3), we see that for any $\zeta < \min(d/\alpha, 2)$, there is a constant $C_{\alpha,\beta,d,v,\zeta}$ such that

$$\begin{aligned} |Y(t, x)| &\leq C_{\alpha,\beta,d,v,\zeta} |x|^{-d} t^{\beta-1} \frac{|\frac{x}{t^{\beta/\alpha}}|^{\alpha\zeta}}{|\frac{x}{t^{\beta/\alpha}}|^{\alpha\zeta+\alpha} + 1} \\ &= C_{\alpha,\beta,d,v,\zeta} t^{\beta-1-\frac{\beta d}{\alpha}} \Theta\left(\frac{x}{t^{\beta/\alpha}}\right). \end{aligned}$$

Therefore, by Lemma 7.3, we have

$$\begin{aligned} &\int_{\mathbb{R}^{2d}} |Y(s, x_1 - x_2)Y(r, y_1 - y_2)| |x_1 - y_1|^{-\kappa} dx_1 dy_1 \\ &\leq C_{\alpha,\beta,d,v,\zeta} (sr)^{\beta-1-\frac{\beta d}{\alpha}} \int_{\mathbb{R}^{2d}} \Theta\left(\frac{x_1 - x_2}{s^{\beta/\alpha}}\right) \Theta\left(\frac{y_1 - y_2}{r^{\beta/\alpha}}\right) |x_1 - y_1|^{-\kappa} dx_1 dy_1 \\ &\leq C_{\alpha,\beta,d,v,\zeta} r^{\beta-1-\frac{\beta d}{\alpha}} s^{\beta-1-\kappa\beta/\alpha} \int_{\mathbb{R}^d} \left(\int_{\mathbb{R}^d} \left|z_1 - \frac{y_1 - x_2}{s^{\beta/\alpha}}\right|^{-\kappa} \Theta(z_1) dz_1\right) \Theta\left(\frac{y_1 - y_2}{r^{\beta/\alpha}}\right) dy_1 \\ &\leq C_{\alpha,\beta,d,v,\zeta} r^{\beta-1-\frac{\beta d}{\alpha}} s^{\beta-1-\kappa\beta/\alpha} \int_{\mathbb{R}^d} \Theta\left(\frac{y_1 - y_2}{r^{\beta/\alpha}}\right) dy_1 \\ &\leq C_{\alpha,\beta,d,v,\zeta} r^{\beta-1} s^{\beta-1-\kappa\beta/\alpha}. \end{aligned}$$

By symmetry, we also have

$$\iint_{\mathbb{R}^{2d}} |Y(s, x_1 - x_2)Y(r, y_1 - y_2)| |x_1 - y_1|^{-\kappa} dx_1 dy_1 \leq C_{\alpha,\beta,d,v,\zeta} s^{\beta-1} r^{\beta-1-\kappa\beta/\alpha}.$$

Now from the fact that $c \leq a$ and $c \leq b$ implies $c \leq \sqrt{ab}$, the lemma follows. □

The following lemma is from [3, Theorem 3.5].

Lemma 7.4: Let T_n be the simplex defined in (5.5). Then for all $h > -1$, it holds that

$$\int_{T_n(t)} [(t - s_n)(s_n - s_{n-1}) \dots (s_2 - s_1)]^h ds = \frac{\Gamma(1+h)^n}{\Gamma(n(1+h) + 1)} t^{n(1+h)}.$$

Proof of Theorem 3.14: Following the same notation and arguments as the proof of Theorem 3.5 until (5.1), we have

$$\begin{aligned} &n! \|f_n(\cdot, \cdot, t, x)\|_{\mathcal{H}^{\otimes n}}^2 \\ &\leq C \frac{1}{n!} \int_{[0,t]^{2n}} ds dr \int_{\mathbb{R}^{2nd}} dy dz g_n(s, y, t, x) g_n(r, z, t, x) \prod_{i=1}^n \Lambda(y_i - z_i) \prod_{i=1}^n \gamma(s_i - r_i). \end{aligned}$$

Furthermore, by Cauchy-Schwarz inequality, we obtain

$$\begin{aligned} &\int_{\mathbb{R}^{2nd}} dy dz g_n(s, y, t, x) g_n(r, z, t, x) \prod_{i=1}^n \Lambda(y_i - z_i) \\ &\leq \left\{ \int_{\mathbb{R}^{2nd}} dy dz g_n(s, y, t, x) g_n(s, z, t, x) \prod_{i=1}^n \Lambda(y_i - z_i) \right\}^{1/2} \\ &\quad \times \left\{ \int_{\mathbb{R}^{2nd}} dy dz g_n(r, y, t, x) g_n(r, z, t, x) \prod_{i=1}^n \Lambda(y_i - z_i) \right\}^{1/2} \end{aligned}$$

Applying Lemma 7.3 to the above two integrals, we have

$$\int_{\mathbb{R}^{2nd}} dydz g_n(s, y, t, x)g_n(r, z, t, x) \prod_{i=1}^n \Lambda(y_i - z_i) \leq C_{\alpha, \beta, d, v, \kappa}^n (\phi(s)\phi(r))^\theta,$$

where

$$\phi(s) := \prod_{i=1}^n (s_{\sigma(i+1)} - s_{\sigma(i)}) \quad \text{and} \quad \phi(r) := \prod_{i=1}^n (r_{\rho(i+1)} - r_{\rho(i)}),$$

with

$$0 < s_{\sigma(1)} < s_{\sigma(2)} < \dots < s_{\sigma(n)} \quad \text{and} \quad 0 < r_{\rho(1)} < r_{\rho(2)} < \dots < r_{\rho(n)}.$$

Hence,

$$\begin{aligned} n! \|f_n(\cdot, \cdot, t, x)\|_{\mathcal{H}^{\otimes n}}^2 &\leq \frac{C_{\alpha, \beta, d, v, \kappa}^n}{n!} \int_{[0, t]^{2n}} \prod_{i=1}^n \gamma(s_i - r_i) (\phi(s)\phi(r))^\theta dsdr \\ &\leq \frac{C_{\alpha, \beta, d, v, \kappa}^n}{n!} \frac{1}{2} \int_{[0, t]^{2n}} \prod_{i=1}^n \gamma(s_i - r_i) (\phi(s)^{2\theta} + \phi(r)^{2\theta}) dsdr \\ &= \frac{C_{\alpha, \beta, d, v, \kappa}^n}{n!} \int_{[0, t]^{2n}} \prod_{i=1}^n \gamma(s_i - r_i) \phi(s)^{2\theta} dsdr \\ &\leq \frac{C_{\alpha, \beta, d, v, \kappa}^n C_t^n}{n!} \int_{[0, t]^n} \phi(s)^{2\theta} ds \\ &= C_{\alpha, \beta, d, v, \kappa}^n C_t^n \int_{T_n(t)} \phi(s)^{2\theta} ds \\ &= \frac{C_{\alpha, \beta, d, v, \kappa}^n C_t^n \Gamma(2\theta + 1) n t^{(2\theta+1)n}}{\Gamma((2\theta + 1)n + 1)}, \end{aligned}$$

where C_t is defined in (2.2). Therefore,

$$n! \|f_n(\cdot, \cdot, t, x)\|_{\mathcal{H}^{\otimes n}}^2 \leq \frac{C_{\alpha, \beta, d, v, \kappa}^n C_t^n}{\Gamma((2\theta + 1)n + 1)},$$

and $\sum_{n \geq 0} n! \|f_n(\cdot, \cdot, t, x)\|_{\mathcal{H}^{\otimes n}}^2$ converges if $\theta > -1/2$. Finally, the condition $\theta > -1/2$, which is equivalent to $\kappa < 2\alpha - \alpha/\beta$, guarantees both condition $\theta > -1$ in Lemma 7.4 and the assumption $\kappa < 2\alpha$ used in Lemma 7.3. This completes the proof of Theorem 3.14. \square

Acknowledgements

Le Chen thanks Francesco Mainardi for some useful discussion and thanks Anatoly N. Kochubei for pointing out Pskhu’s paper [31].

Disclosure statement

No potential conflict of interest was reported by the authors.

Funding

L. Chen is partially supported by the Swiss National Foundation for Scientific Research fellowship [P2ELP2_151796]; Y. Hu is partially supported by a grant from the Simons Foundation [#209206]; J. Huang is supported by the National Science Foundation [grant number DMS-1440140] while in residence at the Mathematical Research Institute in Berkeley, California, during the fall 2015 semester.

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Appendix A. Fox H-function

Definition 1.1: Let m, n, p, q be integers such that $0 \leq m \leq q, 0 \leq n \leq p$. Let $a_i, b_i \in \mathbb{C}$ be complex numbers and let α_j, β_j be positive numbers, $i = 1, 2, \dots, p$ and $j = 1, 2, \dots, q$. Let the set of poles of the gamma functions $\Gamma(b_j + \beta_j s)$ doesn't intersect with that of the gamma functions $\Gamma(1 - a_i - \alpha_i s)$, namely,

$$\left\{ b_{jl} = \frac{-b_j - l}{\beta_j}, l = 0, 1, \dots \right\} \cap \left\{ a_{ik} = \frac{1 - a_i + k}{\alpha_i}, k = 0, 1, \dots \right\} = \emptyset, \quad (\text{A1})$$

for all $i = 1, 2, \dots, p$ and $j = 1, 2, \dots, q$. Denote

$$\mathcal{H}_{p,q}^{m,n}(s) := \frac{\prod_{j=1}^m \Gamma(b_j + \alpha_j s) \prod_{i=1}^n \Gamma(1 - a_i - \alpha_i s)}{\prod_{i=n+1}^p \Gamma(a_i + \alpha_i s) \prod_{j=m+1}^q \Gamma(1 - b_j - \alpha_j s)}.$$



Figure A1. Some illustrations of the path L .

The Fox H -function

$$H_{p,q}^{m,n}(z) \equiv H_{p,q}^{m,n} \left[z \left| \begin{matrix} (a_1, \alpha_1) \cdots (a_p, \alpha_p) \\ (b_1, \beta_1) \cdots (b_q, \beta_q) \end{matrix} \right. \right] \tag{A2}$$

is defined by the following integral

$$H_{p,q}^{m,n}(z) = \frac{1}{2\pi i} \int_L \mathcal{H}_{p,q}^{m,n}(s) z^{-s} ds, \quad z \in \mathbb{C}, \tag{A3}$$

where an empty product in (A3) means 1 and L in (A3) is the infinite contour which separates all the points b_{jl} to the left and all the points a_{ik} to the right of L . Moreover, L has one of the following forms:

- (1) $L = L_{-\infty}$ is a left loop situated in a horizontal strip starting at point $-\infty + i\phi_1$ and terminating at point $-\infty + i\phi_2$ for some $-\infty < \phi_1 < \phi_2 < \infty$;
- (2) $L = L_{+\infty}$ is a right loop situated in a horizontal strip starting at point $+\infty + i\phi_1$ and terminating at point $+\infty + i\phi_2$ for some $-\infty < \phi_1 < \phi_2 < \infty$;
- (3) $L = L_{i\gamma\infty}$ is a contour starting at point $\gamma - i\infty$ and terminating at point $\gamma + i\infty$ for some $\gamma \in (-\infty, \infty)$.

See Figure A1 for some illustrating paths. According to [22, Theorem 1.1], the integral (A3) exists, for example, when

$$\Delta := \sum_{j=1}^q \beta_j - \sum_{i=1}^p \alpha_i \geq 0 \quad \text{and} \quad L = L_{-\infty}, \tag{A4}$$

or when

$$a^* := \sum_{i=1}^n \alpha_i - \sum_{i=n+1}^p \alpha_i + \sum_{j=1}^m \beta_j - \sum_{j=m+1}^q \beta_j \geq 0 \quad \text{and} \quad L = L_{i\gamma\infty}. \tag{A5}$$

We call the poles a_{ik} (see (A1)) of $\Gamma(1 - a_i + \alpha_i s)$, $i = 1, \dots, n$, simple, if

$$\forall i, j, \quad \alpha_j(1 - a_i + k) \neq \alpha_i(1 - a_j + l), \quad i \neq j; \quad i, j = 1, 2, \dots, n; \quad k, l = 0, 1, \dots \tag{A6}$$

Similarly, the poles b_{jl} (see (A1)) of $\Gamma(b_j + \beta_j s)$, $j = 1, \dots, m$, simple, if

$$\forall i, j, \quad \beta_j(b_i + k) \neq \beta_i(b_j + l), \quad i \neq j; \quad i, j = 1, 2, \dots, m; \quad k, l = 0, 1, \dots \tag{A7}$$

Theorem 1.2: I(Part (iii) of Theorem 1.2 in [22]) *Let $L = L_{i\gamma\infty}$, $a^* > 0$, $z \neq 0$, then $H_{p,q}^{m,n}(z)$ is analytic on $\{z : |\arg z| < a^* \pi / 2\}$.*

A.1. Some elementary properties

Property 1.3: (Property 2.2 of [22]) If $n \geq 1$ and $q > m$, then

$$H_{p,q}^{m,n} \left(z \left| \begin{matrix} (a_i, \alpha_i)_{1,p} \\ (b_j, \beta_j)_{1,q-1}, (a_1, \alpha_1) \end{matrix} \right. \right) = H_{p-1,q-1}^{m,n-1} \left(z \left| \begin{matrix} (a_i, \alpha_i)_{2,p} \\ (b_j, \beta_j)_{1,q-1} \end{matrix} \right. \right).$$

And similarly, if $m \geq 1$ and $p > n$, then

$$H_{p,q}^{m,n} \left(z \left| \begin{matrix} (a_i, \alpha_i)_{1,p-1}, (b_1, \beta_1) \\ (b_j, \beta_j)_{1,q} \end{matrix} \right. \right) = H_{p-1,q-1}^{m-1,n} \left(z \left| \begin{matrix} (a_i, \alpha_i)_{1,p-1} \\ (b_j, \beta_j)_{2,q} \end{matrix} \right. \right).$$

Property 1.4: (Property 2.3 of [22]) It holds that

$$H_{p,q}^{m,n} \left(\frac{1}{z} \left| \begin{matrix} (a_i, \alpha_i)_{1,p} \\ (b_j, \beta_j)_{1,q} \end{matrix} \right. \right) = H_{q,p}^{n,m} \left(z \left| \begin{matrix} (1-b_j, \beta_j)_{1,q} \\ (1-a_i, \alpha_i)_{1,p} \end{matrix} \right. \right).$$

Property 1.5: (Property 2.4 of [22]) For $k > 0$, it holds that

$$H_{p,q}^{m,n} \left(z \left| \begin{matrix} (a_i, \alpha_i)_{1,p} \\ (b_j, \beta_j)_{1,q} \end{matrix} \right. \right) = k H_{p,q}^{m,n} \left(z^k \left| \begin{matrix} (a_i, k\alpha_i)_{1,p} \\ (b_j, k\beta_j)_{1,q} \end{matrix} \right. \right).$$

A.2. Asymptotics at zero and infinity

The following two theorems are some basic results on the asymptotic expansions of the Fox H-functions at zero and infinity.

Theorem 1.6: Suppose $H_{p,q}^{m,n}(z)$ satisfies either $\Delta < 0, a^* > 0$ or $\Delta \geq 0$. If the poles of $\Gamma(1 - a_i + \alpha_i s)$ do not coincide, i.e. (A6) holds, then when $z \rightarrow \infty$, we have

$$H_{p,q}^{m,n}(z) \sim \sum_{i=1}^n \sum_{k=0}^{\infty} h_{ik} z^{\frac{a_i-1-k}{\alpha_i}}, \tag{A8}$$

where

$$h_{ik} = \frac{(-1)^k}{k! \alpha_i} \frac{\prod_{j=1}^m \Gamma(b_j + [1 - a_i + k] \frac{\beta_j}{\alpha_i}) \prod_{j=1, i \neq j}^n \Gamma(1 - a_j - [1 - a_i + k] \frac{\alpha_j}{\alpha_i})}{\prod_{j=n+1}^p \Gamma(a_j + [1 - a_i + k] \frac{\alpha_j}{\alpha_i}) \prod_{j=m+1}^q \Gamma(1 - b_j - [1 - a_i + k] \frac{\beta_j}{\alpha_i})}. \tag{A9}$$

Proof: See section 1.5 of [22]. Equation (A8) is asymptotic expansion 1.5.1 of [22]. □

Theorem 1.7: Suppose $H_{p,q}^{m,n}(z)$ satisfies either $\Delta < 0, a^* > 0$ or $\Delta \geq 0$. When $z \rightarrow 0$, we have the following two cases:

(1) If the poles b_{ji} are simple (see (A7)), then

$$H_{p,q}^{m,n}(z) \sim \sum_{j=1}^m \sum_{l=0}^{\infty} l_{ji}^* z^{\frac{b_j+l}{\beta_j}}; \tag{A10}$$

(2) If the poles b_{ji} (see (A1)) of $\Gamma(b_j + \beta_j s), j = 1, \dots, m$, coincide:

$$\exists i, j, \quad \beta_j(b_i + k) = \beta_i(b_j + l), \quad i \neq j; \quad i, j = 1, 2, \dots, m; \quad k, l = 0, 1, \dots,$$

then

$$H_{p,q}^{m,n}(z) \sim \sum'_{j,l} h_{jl}^* z^{\frac{b_j+l}{\beta_j}} + \sum''_{j,l} \sum_{i=0}^{N_{jl}^*-1} H_{jli}^* z^{\frac{b_j+l}{\beta_j}} [\log z]^i, \tag{A11}$$

Here

$$h_{jl}^* = \frac{(-1)^l \prod_{i=1, i \neq j}^m \Gamma(b_i - [b_j + l] \frac{\beta_i}{\beta_j}) \prod_{i=1}^n \Gamma(1 - a_i + [b_j + l] \frac{\alpha_i}{\beta_j})}{l! \beta_j \prod_{i=n+1}^p \Gamma(a_i - [b_j + l] \frac{\alpha_i}{\beta_j}) \prod_{i=m+1}^q \Gamma(1 - b_i + [b_j + l] \frac{\beta_i}{\beta_j})}; \tag{A12}$$

$\sum'_{j,l}$ is summation over j, l such that the b_{jl} do not coincide; $\sum''_{j,l}$ is the summation over j, l such that b_{jl} coincide with order N_{jl}^* ;

$$H_{jli}^* = \frac{1}{(N_{jl}^* - 1)!} \sum_{n=i}^{N_{jl}^*-1} (-1)^i \binom{N_{jl}^* - 1}{n} \binom{n}{i} [\mathcal{H}_1^*(b_{jl})]^{(N_{jl}^*-1-n)} [\mathcal{H}_2^*(b_{jl})]^{(n-i)}, \tag{A13}$$

where $N_{jl}^* - 1 - n$ and $n - i$ are orders of derivative;

$$\mathcal{H}_1^*(s) = (s - b)^{N^*} \prod_{j=1}^{j_{N^*}} \Gamma(b_j + \beta_j s), \quad \mathcal{H}_2^*(s) = (s - b)^{N^*} \prod_{j=1}^{j_{N^*}} \Gamma(b_j + \beta_j s) \mathcal{H}_{p,q}^{m,n}(s), \tag{A14}$$

where b is the pole with order N^* .

Proof: See section 1.8 of [22]. Equation (A10) is asymptotic expansion 1.8.1 of [22]. Equation (A11) is asymptotic expansion 1.8.2 of [22]. \square

A.3. A convolution property

The following theorem is a simplified version of Theorems 2.9 and 2.10 in [23], which is sufficient for our use. We need another parameter for the Fox H-function (A2):

$$\mu = \sum_{j=1}^q b_j - \sum_{i=1}^p a_i + \frac{p - q}{2}. \tag{A15}$$

Theorem 1.8: Let (a_1^*, Δ_1, μ_1) and (a_2^*, Δ_2, μ_2) be the constants (a^*, Δ, μ) defined in (A5), (A4) and (A15) for the following two Fox H-functions:

$$H_{p,q}^{m,n} \left(x \left| \begin{matrix} (a_i, \alpha_i)_{1,p} \\ (b_j, \beta_j)_{1,q} \end{matrix} \right. \right) \quad \text{and} \quad H_{P,Q}^{M,N} \left(x \left| \begin{matrix} (d_i, \delta_i)_{1,P} \\ (c_j, \gamma_j)_{1,Q} \end{matrix} \right. \right),$$

respectively. Denote

$$A_1 = \min_{1 \leq i \leq n} \frac{1 - \Re(a_i)}{\alpha_i}, \quad B_1 = \min_{1 \leq j \leq m} \frac{\Re(b_j)}{\beta_j},$$

$$A_2 = \min_{1 \leq j \leq M} \frac{\Re(c_j)}{\gamma_j}, \quad B_2 = \min_{1 \leq i \leq N} \frac{1 - \Re(d_i)}{\delta_i},$$

with the convention that $\min(\phi) = +\infty$. If either of the following four conditions holds

- (1) $a_1^* > 0$ and $a_2^* \geq 0$ and $\Delta_2 \neq 0$;

- (2) $a_1^* \geq 0$ and $a_2^* > 0$ and $\Delta_1 \neq 0$;
- (3) $a_1^* = \Delta_1 = 0$, $\Re(\mu_1) < -1$ and $a_2^* > 0$;
- (4) $a_2^* = \Delta_2 = 0$, $\Re(\mu_2) < -1$ and $a_1^* > 0$;
- (5) $a_1^* = \Delta_1 = 0$, $\Re(\mu_1) < -1$ and $a_2^* = \Delta_2 = 0$, $\Re(\mu_2) < -1$,

and if

$$A_1 + B_1 > 0, \quad A_2 + B_2 > 0, \quad A_1 + A_2 > 0, \quad B_1 + B_2 > 0, \tag{A16}$$

then, for all $z > 0$, $x \in \mathbb{R}$,

$$\begin{aligned} H_{p+P,q+Q}^{m+M,n+N} \left(zx \left| \begin{matrix} (a_i, \alpha_i)_{1,n}, (d_i, \delta_i)_{1,p}, (a_i, \alpha_i)_{n+1,p} \\ (b_j, \beta_j)_{1,m}, (c_j, \gamma_j)_{1,q}, (b_j, \beta_j)_{m+1,q} \end{matrix} \right. \right) \\ = \int_0^\infty H_{p,q}^{m,n} \left(zt \left| \begin{matrix} (a_i, \alpha_i)_{1,p} \\ (b_j, \beta_j)_{1,q} \end{matrix} \right. \right) H_{P,Q}^{M,N} \left(\frac{x}{t} \left| \begin{matrix} (d_i, \delta_i)_{1,p} \\ (c_j, \gamma_j)_{1,q} \end{matrix} \right. \right) \frac{dt}{t}. \end{aligned}$$

Proof: By Property 1.4,

$$H_{P,Q}^{M,N} \left(\frac{x}{t} \left| \begin{matrix} (d_i, \delta_i)_{1,p} \\ (c_j, \gamma_j)_{1,q} \end{matrix} \right. \right) = H_{Q,P}^{N,M} \left(\frac{t}{x} \left| \begin{matrix} (1-c_j, \gamma_j)_{1,q} \\ (1-d_i, \delta_i)_{1,p} \end{matrix} \right. \right). \tag{A17}$$

If both $a_1^* > 0$ and $a_2^* > 0$, then one can apply Theorem 2.9 of [23] with $\eta = 0$, $\sigma = 1$, $w = 1/x$, and with the following replacements: $N \rightarrow M$, $M \rightarrow N$, $P \rightarrow Q$, $Q \rightarrow P$, $c_j \rightarrow 1 - c_j$, $d_i \rightarrow 1 - d_i$. When $a_1^* > 0$ but $a_2^* = 0$ and $\Delta_2 \neq 0$, because both z and x are real numbers, Theorem 2.9 of [22] still holds (see the paragraph before Theorem 2.10 of [22] on p.59). Therefore, we have proved the theorem under conditions (1) or (2).

If either of conditions (3)–(5) holds, we apply Theorem 2.10 of [23] in the same way. Note that the parameters μ for both Fox H-functions in (A17) are equal. \square

A.4. Some integral transforms

The following result on the Laplace transform of the Fox H-function is used in this paper. Denote

$$(\mathbb{L}f)(t) := \int_0^\infty f(x)e^{-tx} dx, \quad t \in \mathbb{C}.$$

Theorem 1.9: (Part of Corollary 2.3.1 of [22]) Suppose that $a^* > 0$. Assume that $w \in \mathbb{C}$, $a > 0$ and $\sigma > 0$ are such that

$$\sigma \min_{1 \leq j \leq m} \frac{\Re(b_j)}{\beta_j} + \Re(w) > -1. \tag{A18}$$

Then

$$\left[\mathbb{L}x^w H_{p,q}^{m,n} \left(ax^\sigma \left| \begin{matrix} (a_i, \alpha_i)_{1,p} \\ (b_j, \beta_j)_{1,q} \end{matrix} \right. \right) \right] (t) = \frac{1}{t^{w+1}} H_{p+1,q}^{m,n+1} \left(\frac{a}{t^\sigma} \left| \begin{matrix} (-w, \sigma), (a_i, \alpha_i)_{1,p} \\ (b_j, \beta_j)_{1,q} \end{matrix} \right. \right).$$

We also need the following convolution result, which is related to the Hankel transform of the Fox H-function.

Theorem 1.10: (Corollary 2.5.1 of [22]) Let $a^* > 0$ or $a^* = \Delta = 0$ and $\Re(\mu) < -1$. Let $\eta, w \in \mathbb{C}$, $\tau > 0$ and $\sigma > 0$ be such that

$$\begin{aligned} \sigma \Re(\eta) + \Re(w) + \tau \min_{1 \leq j \leq m} \frac{\Re(b_j)}{\beta_j} > -1, \\ \tau \min_{1 \leq i \leq n} \frac{1 - \Re(a_i)}{\alpha_i} > \Re(w) - \frac{\sigma}{2} + 1, \end{aligned}$$

and

$$\Re(\eta) > -1/2.$$

Then for all $a > 0$ and $b > 0$,

$$\begin{aligned} & \int_0^\infty (xt)^w J_\eta (a(xt)^\sigma) H_{p,q}^{m,n} \left(bt^\tau \left| \begin{matrix} (a_i, \alpha_i)_{1,p} \\ (b_j, \beta_j)_{1,q} \end{matrix} \right. \right) dt \\ &= \frac{1}{2\sigma x} \left(\frac{2}{a} \right)^{\frac{w+1}{\sigma}} H_{p+2,q}^{m,n+1} \left(\frac{b}{x^\tau} \left(\frac{2}{a} \right)^{\tau/\sigma} \left| \begin{matrix} \left(1 - \frac{w+1}{2\sigma} - \frac{\eta}{2}, \frac{\tau}{2\sigma}\right), (a_i, \alpha_i)_{1,p}, \left(1 - \frac{w+1}{2\sigma} + \frac{\eta}{2}, \frac{\tau}{2\sigma}\right) \\ (b_j, \beta_j)_{1,q} \end{matrix} \right. \right), \quad x > 0. \end{aligned}$$

A.5. Riemann–Liouville fractional derivatives

Recall that the Riemann–Liouville fractional derivative of order $\alpha \in (0, 1)$ is defined in (4.1). The following results are used several times in this paper, which is a special case of part (i) of Theorem 2.8 of [22].

Theorem 1.11: Let $\alpha \in (0, 1)$, $w \in \mathbb{C}$ and $\sigma > 0$. If $a^* > 0$ and (A18) holds, then

$$\left[D_{0+}^\alpha t^w H_{p,q}^{m,n} \left(t^\sigma \left| \begin{matrix} (a_i, \alpha_i)_{1,p} \\ (b_j, \beta_j)_{1,q} \end{matrix} \right. \right) \right] (x) = x^{w-\alpha} H_{p+1,q+1}^{m,n+1} \left(x^\sigma \left| \begin{matrix} (-w, \sigma), (a_i, \alpha_i)_{1,p} \\ (b_j, \beta_j)_{1,q}, (-w+\alpha, \sigma) \end{matrix} \right. \right).$$

A.6. Some special cases

The Mittag–Leffler function is a special case of the Fox H-function (see (2.9.27) of [22]):

$$E_{\rho,\mu}(x) = H_{1,2}^{1,1} \left(-x \left| \begin{matrix} (0,1) \\ (0,1), (1-\mu,\rho) \end{matrix} \right. \right), \quad \rho > 0, \mu \in \mathbb{C}. \quad (\text{A19})$$

The $\cos(\cdot)$ function can be represented as (see [22, (2.9.8)]):

$$\cos(z) = \sqrt{\pi} H_{0,2}^{1,0} \left(\frac{z^2}{4} \left| \begin{matrix} \overline{} \\ (0,1), (1/2,1) \end{matrix} \right. \right). \quad (\text{A20})$$

The Bessel function of the first kind $J_\eta(z)$ is equal to (see (2.9.18) of [22])

$$J_\eta(z) = \left(\frac{2}{z} \right)^a H_{0,2}^{1,0} \left(\frac{z^2}{4} \left| \begin{matrix} \overline{} \\ \left(\frac{a+\eta}{2}, 1\right), \left(\frac{a-\eta}{2}, 1\right) \end{matrix} \right. \right). \quad (\text{A21})$$

Another special case is (see (2.9.4) of [22])

$$H_{0,1}^{1,0} \left(z \left| \begin{matrix} \overline{} \\ (b,\beta) \end{matrix} \right. \right) = \frac{1}{\beta} z^{b/\beta} \exp(-z^{1/\beta}). \quad (\text{A22})$$