

How Does Data Freshness Affect Real-time Supervised Learning?

Md Kamran Chowdhury Shisher and Yin Sun
Dept. of ECE, Auburn University

Question 1: Does Learning Error Increase with Data Staleness?

Theoretical and Experimental Findings:

Case 1: If the feature and target data sequence is a **Markov** chain, then

- Learning errors (**Training error and Inference error**) **increase monotonically** as **feature ages**.

Case 2: If The feature and target data sequence is **far from Markovian** (due to **Communication delay, Response delay, and long-range dependence**), then

- Learning errors **may not increase monotonically** as **feature becomes stale**.

Age of information (Aol): Time difference between the **current time** and the **generation time** of the **freshest received feature**.

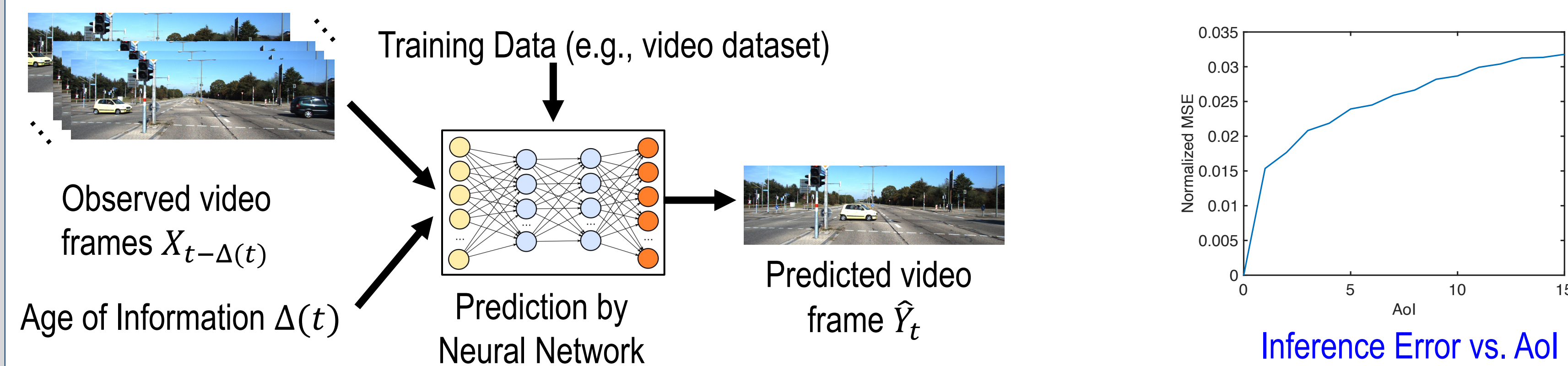
Theorem 1: The learning error is the **difference of two increasing functions** of **Aol δ** .

$$p(\delta) = g_1(\delta) - g_2(\delta).$$

If the data sequence is close to **Markovian**, function $g_2(\delta)$ is close to **0**.

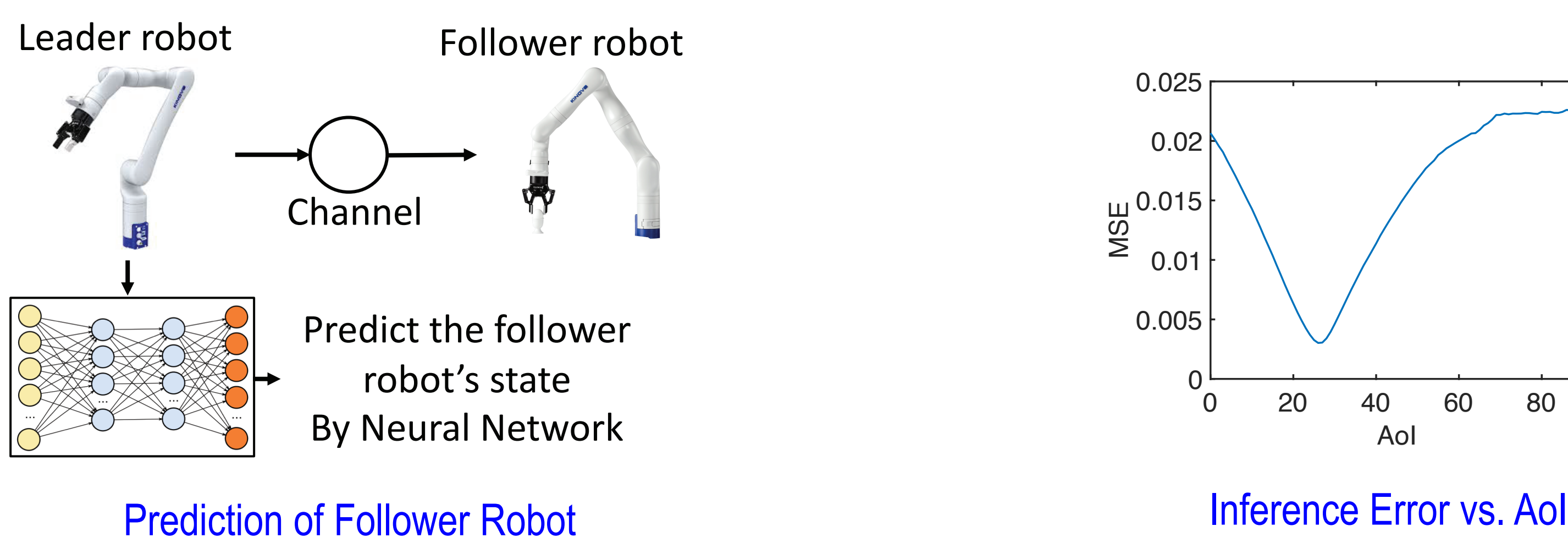
Theorem 1 is proved by using **information theoretic** approach.

Inference Error increases with Aol in Video Prediction



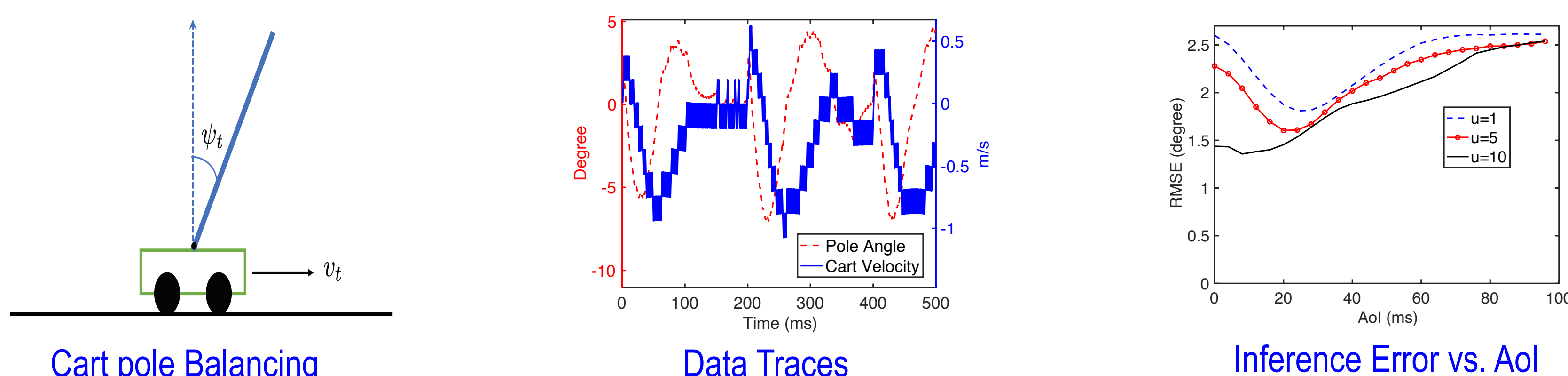
Video sequence is approximately a **Markov chain**.

Robot State Prediction in a Leader-follower Robotic System



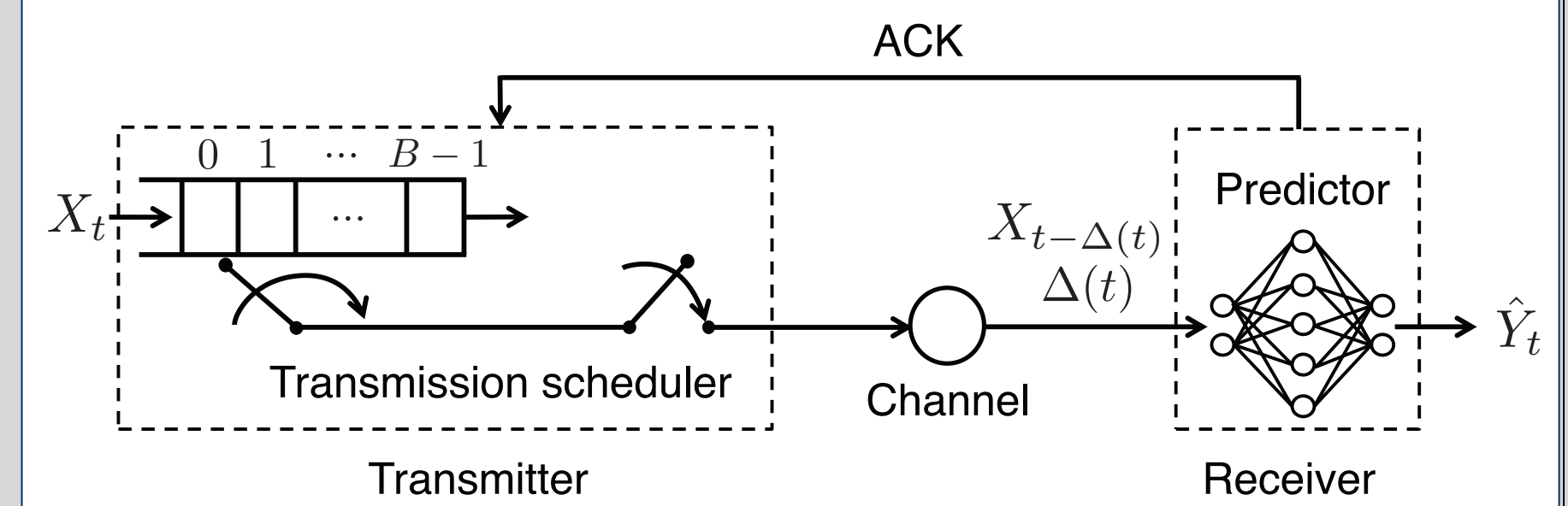
Inference Error decreases in the $Aol \leq 25$ and increases when $Aol \geq 25$.

Actuator State Prediction under Response Delay



- Data traces show **25-30 ms** response delay.
- The data sequence is **non-Markovian**.
- The inference error becomes **increasing function** as the length u of feature $X_t = \{s_t, \dots, s_{t-u+1}\}$ **increases**.

Question 2: Optimal Feature Transmission



Findings:

- Sending **old feature** could be **better**.
- Send another feature when Gittins index $\gamma(\Delta(t))$ exceeds a threshold.

Optimal Scheduling Policy

Theorem 2: The **optimal policy** is

$$S_{i+1} = \inf_{t \in \mathbb{Z}} \{t \geq D_i : \gamma(\Delta(t)) \geq p_{opt}\},$$

where optimal objective value p_{opt} is a solution of the following **fixed point equation** of β :

$$\beta = \frac{\mathbb{E} \left[\sum_{t=D_i(\beta)}^{D_{i+1}(\beta)-1} p(\Delta(t)) \right]}{\mathbb{E}[D_{i+1}(\beta) - D_i(\beta)]}$$

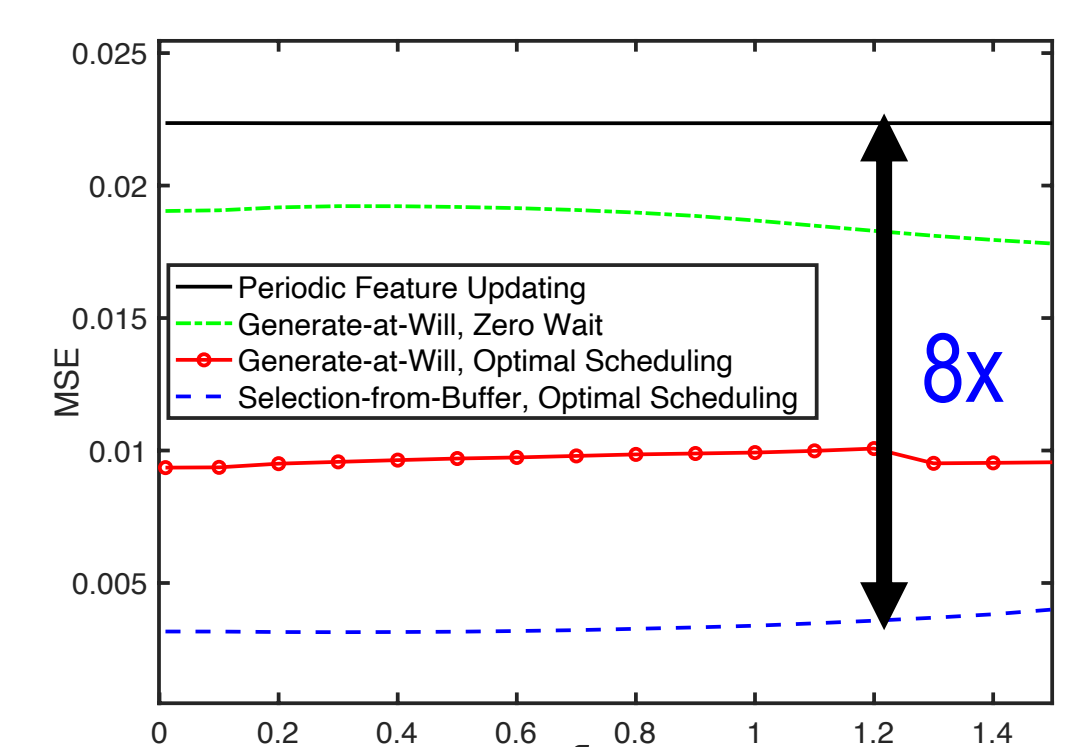
Low Complexity Algorithm

The $(i+1)$ -th feature is sent at the earliest time slot t satisfying two conditions:

- The i -th feature has already been delivered by time slot t , i.e., $t \geq D_i$.
- The **Gittins index** $\gamma(\Delta(t))$ exceeds p_{opt} .
- The **optimal position of the buffer** is **constant** for all i and is solved analytically.

Whittle index policy is designed for **Multi-source Scheduling**.

Numerical Result



8 times performance gain.

References

- [1] MKC Shisher and Y Sun, "How Does Data Freshness Affect Real-time Supervised Learning", *ACM Mobihoc*, 2022.
- [2] Y Sun and B Cyr, "Sampling for Data Freshness Optimization: Non-linear Age Functions", *JCN*, 2019.
- [3] MKC Shisher, H Qin, L Yang, F Yan, and Y Sun, "The Age of Correlated Features in Supervised Learning Based Forecasting", *IEEE Infocom Aol Workshop*, 2021.
- [4] J Gittins, K Glazebrook, and R Weber. "Multi-armed bandit allocation indices". *John Wiley & Sons*, 2011.